TMP119 具有 SMBus™ 和 I²C 兼容接口的超高精度、低功耗数字温度传感器

1 特性

- TMP119 高精度温度传感器
  - 0°C 至 45°C 范围内为 ±0.03°C（典型值）
  - 0°C 至 45°C 范围内为 ±0.08°C（最大值）
  - -25°C 至 85°C 范围内为 ±0.09°C（最大值）
  - -40°C 至 85°C 范围内为 ±0.12°C（最大值）
  - -55°C 至 125°C 范围内为 ±0.15°C（最大值）
  - -55°C 至 150°C 范围内为 ±0.2°C（最大值）
- 工作温度范围：-55°C 至 150°C
- 低功耗：
  - 3.5 µA、1Hz 转换周期
  - 150nA 关断电流
- 电源电压范围：
  - -55°C 至 70°C 范围内为 1.7V 至 5.5V
  - -55°C 至 150°C 范围内为 1.8V 至 5.5V
- 16 位分辨率：0.0078°C (1LSB)
- 可编程温度警报限值
- 可选择的平均值
- 应力耐受性
- 用于系统校正的数字失调电压
- 通用 EEPROM：48 位
- NIST 可追溯性
- 与 SMBus™、I²C 接口兼容
- 医疗级别：有助于满足 ASTM E1112 和 ISO 80601-2-56 的要求
- RTD 替代产品：PT100、PT500、PT1000

2 应用

- 电子温度计
- 无线环境传感器
- 恒温器
- 汽车类测试设备
- 可穿戴健身和活动监测仪
- 冷链资产跟踪
- 燃气表和热量计
- 温度变送器

3 说明

TMP119 是一款高精度数字温度传感器。该器件旨在满足 ASTM E1112 和 ISO 80601 对医用电子温度计的精度要求。TMP119 可提供 16 位温度结果，具有 0.0078°C 的分辨率，且无需校准即可在 0°C 到 45°C 的温度范围内实现高达 ±0.08°C 的精度。TMP119 具有可兼容 I²C 和 SMBus™ 的接口，具有可编程警报功能，在单路总线上最多可支持四个器件，包含用于器件编程的集成式 EEPROM 和用于通用应用的额外 48 位存储器。TMP119 的工作电压范围为 1.7V 至 5.5V，通常在 1Hz 转换周期内消耗 3.5 µA 电流。

对于非医疗应用，TMP119 可用作 Platinum RTD 的单芯片数字替代产品。TMP119 可实现不逊于 AA 类 RTD 的精度，而且其功耗也仅为 PT100 RTD 通常所需功耗的几分之一。TMP119 摒弃了 RTD 的许多复杂功能，如精密基准、匹配的线迹、复杂的算法和校准，从而简化了设计工作。该器件设计可耐受应力，在 PCB 制造过程中常见的典型应力（包括器件焊接、成型、底层填料和电路板弯曲）下具有稳健性能。

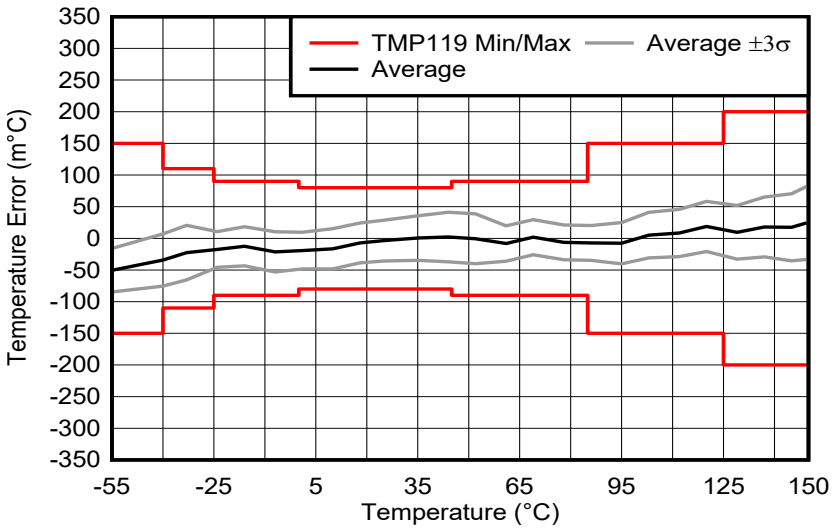
TMP119 装置在生产调试阶段经过 100% 测试，可通过 NIST 进行追溯，且使用经 ISO/IEC 17025 认证标准校准的设备进行了验证。

封装信息

器件型号	封装(1)	封装尺寸(2)
TMP119	YBG（DSBGA，6）	0.95mm x 1.488mm

(1) 有关所有可选封装，请参阅 节 11。
(2) 封装尺寸（长 × 宽）为标称值，并包括引脚（如适用）。

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YBG 温度精度

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Table of Contents

1 特性 1
2 应用 1
3 说明 1
4 Device Comparison 4
5 Pin Configuration and Functions 5
6 Specifications 6
6.1 Absolute Maximum Ratings 6
6.2 ESD Ratings 6
6.3 Recommended Operating Conditions 6
6.4 Thermal Information 6
6.5 Electrical Characteristics 7
6.6 Switching Characteristics 8
6.7 Two-Wire Interface Timing 8
6.8 Timing Diagram 10
6.9 Typical Characteristics 10
7 Detailed Description 13
7.1 Overview 13
7.2 Functional Block Diagram 13
7.3 Feature Description 14
7.4 Device Functional Modes 16
7.5 Programming 20
8 Application and Implementation 27
8.1 Application Information 27
8.2 Typical Application 28
8.3 Power Supply Recommendations 30
8.4 Layout 30
8.5 Register Map 32
9 Device and Documentation Support 40
9.1 Documentation Support 40
9.2 接收文档更新通知 40
9.3 支持资源 40
9.4 Trademarks 40
9.5 静电放电警告 40
9.6 术语表 40
10 Revision History 40
11 Mechanical, Packaging, and Orderable Information 41

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4 Device Comparison

表 4-1. Device Options

Feature	TMP114	TMP116	TMP116N	TMP117	TMP117M	TMP117N	TMP119
VDD Range (V)	1.08 - 1.98	3.0 - 3.6	3.0 - 3.6	1.7 - 5.5	1.7 - 5.5	1.7 - 5.5	1.7 - 5.5
I_{AVG} @ 1Hz	0.63	3.5	3.5	3.5	3.5	3.5	3.5
I_{Q_ACTIVE} (µ A)	68	135	135	135	135	135	135
I_{SB} (µ A)	0.26	1.25	1.25	1.25	1.25	1.25	1.25
I_{SD} (µ A)	0.16	0.25	0.25	0.25	0.25	0.25	0.25
Accuracy							
0°C to 45°C (typ)	0.1	0.1	0.2	0.05	0.05	0.1	0.03
0°C to 45°C (max)	0.2	0.2	0.3	0.1	0.1	0.2	0.08
-55°C (max)	-	-	-	0.25	-	0.3	0.15
-40°C (max)	0.5	0.25	0.4	0.15	-	0.2	0.11
-20°C (max)	0.5	0.25	0.3	0.1	-	0.2	0.09
-10°C (max)	0.3	0.2	0.3	0.1	-	0.2	0.09
-0°C (max)	0.3	0.2	0.3	0.1	0.15	0.2	0.08
20°C (max)	0.2	0.2	0.3	0.1	0.1	0.2	0.08
45°C (max)	0.2	0.2	0.3	0.1	0.1	0.2	0.08
60°C (max)	0.3	0.2	0.3	0.15	0.15	0.2	0.09
85°C (max)	0.5	0.2	0.3	0.2	0.2	0.2	0.15
100°C (max)	0.5	0.25	0.4	0.2	-	0.2	0.15
125°C (max)	0.5	0.3	0.4	0.25	-	0.25	0.2
150°C (max)	-	-	-	0.3	-	0.3	0.2
Packaging							
Dimensions [mm ×mm xmm]	PICOSTAR: 0.76 x 0.76 x 0.15	WSON: 2.0 x 2.0 x 0.8		BGA: 1.49 x 0.95 x 0.531 WSON: 2.0 x 2.0 x 0.8			BGA: 1.49 x 0.95 x 0.525
Features							
Address #	4	4	4	4	4	4	4
Address Programming	Factory Set	ADD0 Pin	ADD0 Pin	ADD0 Pin	ADD0 Pin	ADD0 Pin	ADD0 Pin
NIST Traceable	No	Yes	Yes	Yes	Yes	Yes	Yes

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5 Pin Configuration and Functions

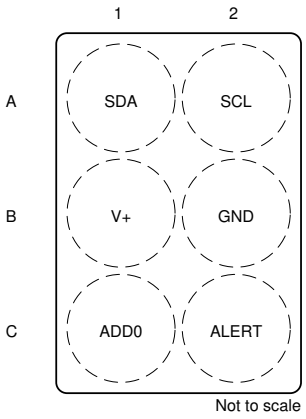


图 5-1. YBG Package 6-Pin DSBGA Top View

表 5-1. Pin Functions

PIN		TYPE	DESCRIPTION
NAME	DSBGA		
ADD0	C1	I	Address select. Connect to GND, V+, SDA, or SCL.
ALERT	C2	O	Overtemperature alert or data-ready signal. This open-drain output requires a pullup resistor if used.
GND	B2	—	Ground
SCL	A2	I	Serial clock
SDA	A1	I/O	Serial data input and open-drain output. Requires a pullup resistor.
V+	B1	I	Supply voltage

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6 Specifications

6.1 Absolute Maximum Ratings

Over free-air temperature range unless otherwise noted(1)

		MIN	MAX	UNIT
Supply voltage	V+	–0.3	6	V
Voltage at	SCL, SDA, ALERT and ADD0	–0.3	6	V
Operating junction temperature, T_J		–55	155	°C
Storage temperature, T_{stg}		–65	155	°C

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

6.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101(2)	±1000	

(1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

		MIN	NOM	MAX	UNIT
V+	Supply voltage, T_A = -55 °C to 150 °C	1.8	3.3	5.5	V
V+	Supply voltage, T_A = -55 °C to 70 °C	1.7		5.5	V
$V_{I/O}$	SCL, SDA, ALERT and ADD0	0		5.5	V
T_A	Operating free-air temperature	–55		150	°C

6.4 Thermal Information

THERMAL METRIC(1)		TMP119 YBG (DSBGA) 6 PINS	UNITS
$R_{\theta JA}$	Junction-to-ambient thermal resistance	133.2	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	1.0	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	40.9	°C/W
ψ_{JT}	Junction-to-top characterization parameter	0.1	°C/W
ψ_{JB}	Junction-to-board characterization parameter	40.7	°C/W
M_T	Thermal Mass	0.7	mJ/°C

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application note.

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6.5 Electrical Characteristics

Over free-air temperature range and V+ = 1.7V to 5.5V for T_A = –55°C to 70°C, or V+ = 1.8V to 5.5V for T_A = –55°C to 150°C (unless otherwise noted); Typical specifications are at T_A = 25°C and V+ = 3.3V (unless otherwise noted)

PARAMETER			TEST CONDITIONS		MIN	TYP	MAX	UNIT
TEMPERATURE TO DIGITAL CONVERTER								
	Temperature accuracy	TMP119	0°C to 45°C	8 averages 1-Hz conversion cycle I^2C Input voltages: $V_{IL} \leqslant 0.05 * V+$, $V_{IH} \geqslant 0.95 * V+$	–0.08	±0.03	0.08	°C
			–25°C to 85°C		–0.09	±0.03	0.09	
			–40°C to 85°C		–0.12	±0.06	0.12	
			–55°C to 125°C		–0.15	±0.06	0.15	
			–55°C to 150°C		–0.2	±0.06	0.2	
		TMP119M	0°C to 45°C		–0.08	±0.03	0.08	
			–20°C to 65°C		–0.09	±0.03	0.09	
	DC power supply sensitivity		One-shot mode, 8 internal averages			6		m°C/V
	Response Time	Response Time	$t_{63\%}$ step Stirred liquid 31mil thick rigid PCB	$t_{63\%}$ step Stirred liquid 31mil thick rigid PCB		1		s
	Gain Error		Maximum Temp Error Drift over 10°C		–0.04		0.04	°C
	Temperature resolution (LSB)					7.8125		m°C
	Repeatability(1)		V+ = 3.3 V 8 averages 1-Hz conversion cycle			±1		LSB
	Long-term stability and drift		1000 hours at 150°C(2)			±0.03		°C
	Temperature cycling and hysteresis(3)		8 Averages			±2		LSB
	Conversion time		No internal averages		13	15.5	17.5	ms
DIGITAL INPUT/OUTPUT								
	Input capacitance					4		pF
V_{IH}	Input logic high level		SCL, SDA, ADD0		0.7 * (V+)			V
V_{IL}	Input logic low level		SCL, SDA, ADD0				0.3 * (V+)	V
I_{IN}	Input leakage current				–0.1		0.1	µA
V_{OL}	SDA and ALERT output logic low level		I_{OL} = –3mA				0.4	V

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Over free-air temperature range and V+ = 1.7V to 5.5V for T_A = –55°C to 70°C, or V+ = 1.8V to 5.5V for T_A = –55°C to 150°C (unless otherwise noted); Typical specifications are at T_A = 25°C and V+ = 3.3V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER SUPPLY						
I_{Q_ACTIVE}	Quiescent current during active conversion	Active Conversion, serial bus inactive		135	220	µA
I_Q	Quiescent current	Duty cycle 1Hz, averaging mode off, serial bus inactive. T_A = 25°C		3.5	5	µA
		Duty cycle 1Hz, 8 averaging mode on, serial bus inactive. T_A = 25°C		16	22	
		Duty cycle 1Hz, averaging mode off, serial bus active, SCL frequency = 400kHz		15		
I_{SB}	Standby current(4)	Serial bus inactive. SCL, SDA, and ADD0 = V+. T_A = 25°C		1.25	2	µA
I_{SD}	Shutdown current	Serial bus inactive, SCL, SDA, and ADD0 = V+. T_A = 25°C		0.15	0.35	µA
	Shutdown current	Serial bus inactive, SCL, SDA and ADD0 = V+, T_A = 150°C			5	µA
	Shutdown current	Serial bus active, SCL frequency = 400kHz, ADD0 = V+		17		µA
I_{EE}	EEPROM write quiescent current	ADC conversion off; serial bus inactive		240		µA
V_{POR}	Power-on-reset threshold voltage	Supply rising		1.6		V
	Brownout detect	Supply falling		1.1		V
t_{RESET}	Reset Time	Time required by device to reset		1.5		ms

(1) Repeatability is the ability to reproduce a reading when the measured temperature is applied consecutively, under the same conditions.
(2) Long term stability is determined using accelerated operational life testing at a junction temperature of 150°C.
(3) Hysteresis is defined as the ability to reproduce a temperature reading as the temperature varies from room → hot →room→cold→ room. The temperatures used for this test are -55°C, 25°C, and 150°C.
(4) Quiescent current between conversions

6.6 Switching Characteristics

Over free-air temperature range and V+ = 1.7V to 5.5V for T_A = –55°C to 70°C, or V+ = 1.8V to 5.5V for T_A = –55°C to 150°C (unless otherwise noted); Typical specifications are at T_A = 25°C and V+ = 3.3V (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
EEPROM					
Programming time			7		ms
Number of writes		1,000	50,000		Times
Data retention time		10	100		Years

6.7 Two-Wire Interface Timing

Over free-air temperature range and V+ = 1.7V to 5.5V for T_A = –55°C to 70°C, or V+ = 1.8V to 5.5V for T_A = –55°C to 150°C (unless otherwise noted)

		STANDARD		FAST-MODE		UNIT
		MIN	MAX	MIN	MAX	
f_{SCL}	SCL operating frequency	1		1	400	KHz
t_{BUF}	Bus free time between STOP and START conditions			1300		ns
$t_{HD;STA}$	Hold time after repeated START condition. After this period, the first clock is generated(1)	5		600		ns
$t_{SU;STA}$	Repeated START condition setup time			600		ns

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Over free-air temperature range and V+ = 1.7V to 5.5V for T_A = –55°C to 70°C, or V+ = 1.8V to 5.5V for T_A = –55°C to 150°C (unless otherwise noted)

		STANDARD		FAST-MODE		UNIT
		MIN	MAX	MIN	MAX	
$t_{SU;STO}$	STOP condition setup time			600		ns
$t_{HD;DAT}$	Data hold time			0		ns
$t_{VD;DAT}$	Data valid time(2)				0.9	µs
$t_{SU;DAT}$	Data setup time			100		ns
t_{LOW}	SCL clock low period			1300		ns
t_{HIGH}	SCL clock high period			600		ns
t_F – SDA	Data fall time			20 × (V+ / 5.5)	300	ns
t_F, t_R – SCL	Clock fall and rise time				300	ns
t_R	Rise time for SCL ≤100 kHz				1000	ns
	Serial bus timeout (SDA bus released if there is no clock)			20	40	ms

(1) The maximum $t_{HD;DAT}$ could be 0.9 µs for Fast-Mode, and is less than the maximum $t_{VD;DAT}$ by a transition time.
(2) $t_{VD;DAT}$ = time for data signal from SCL "LOW" to SDA output ("HIGH" to "LOW", depending on which is worse).

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6.8 Timing Diagram

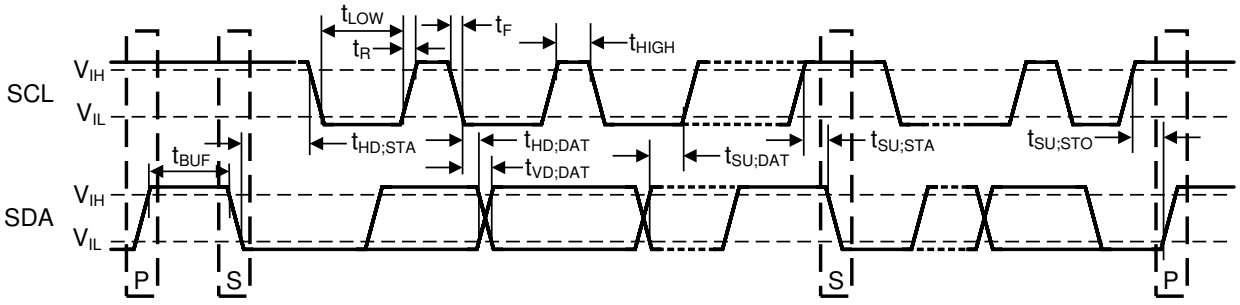
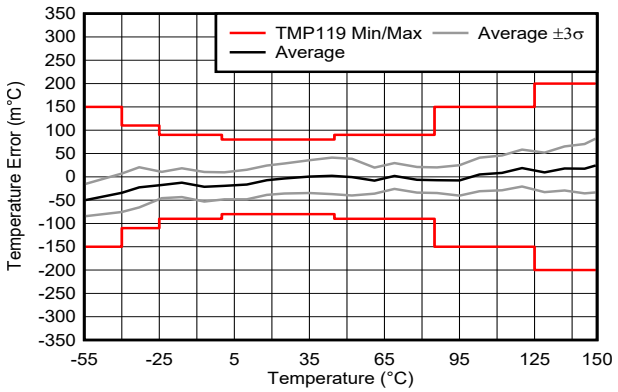


图 6-1. Two-Wire Timing Diagram

6.9 Typical Characteristics

at T_A = 25°C, V+ = 3.3V, and measurement taken in oil bath (unless otherwise noted)



1Hz conversion cycle, 8 averages mode

图 6-2. YBG Package Temperature Error vs Temperature

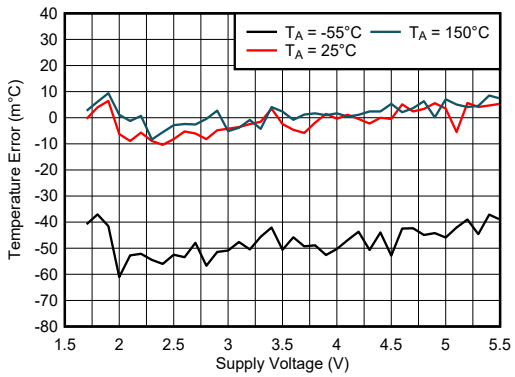


图 6-3. Temperature Error vs Supply Voltage

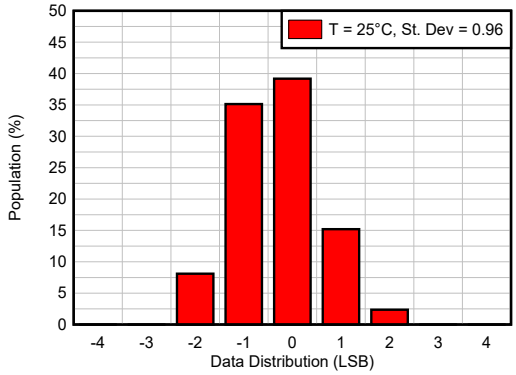
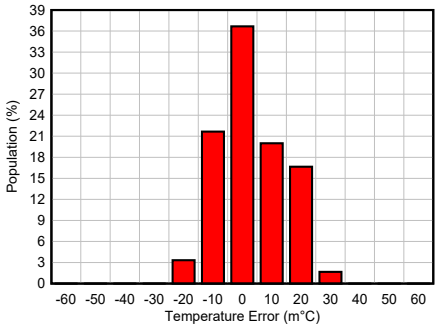


图 6-4. Data Reading Distribution (No Averaging, V+ = 3.3V)



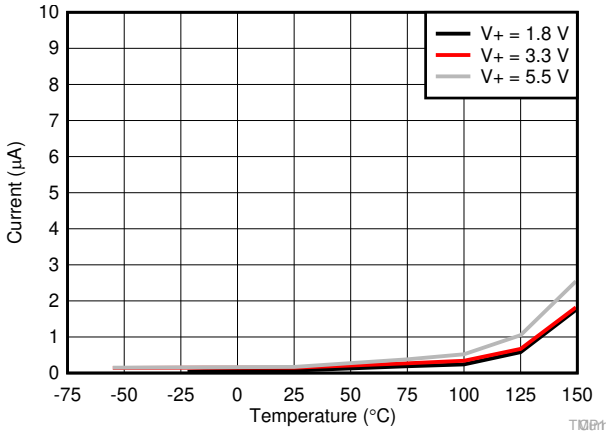
T_A = 25°C. V+ = 3.3V. One-shot mode with averaging = 8.

图 6-5. Typical Temperature Distribution Error

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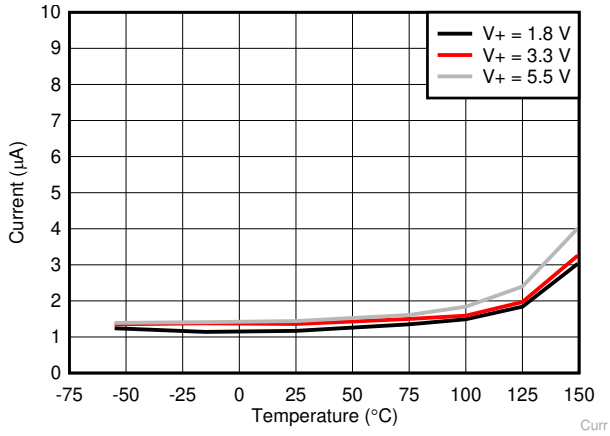
6.9 Typical Characteristics (continued)

at T_A = 25°C, V+ = 3.3V, and measurement taken in oil bath (unless otherwise noted)



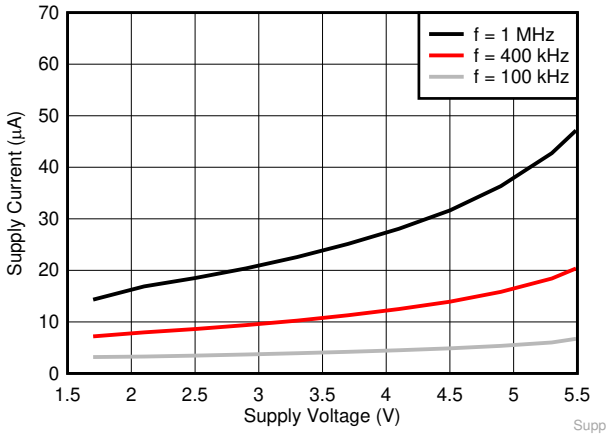
Serial bus inactive

图 6-6. Quiescent Current in Shutdown Mode



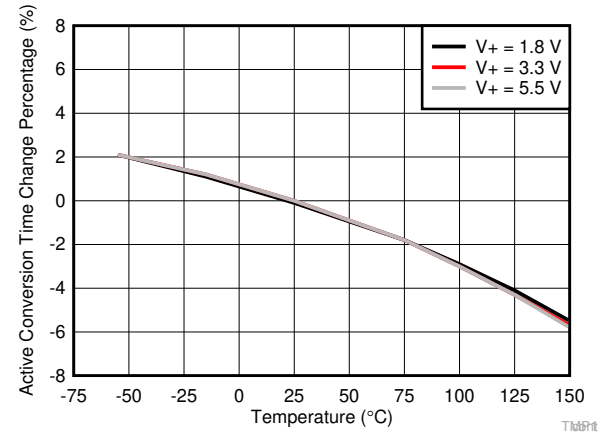
Serial bus inactive

图 6-7. Quiescent Current in Standby Mode



SCL pin clocked

图 6-8. Quiescent Current in Shutdown Mode



Normalized to 25°C and V+ = 3.3V

图 6-9. Active Conversion Time vs Temperature

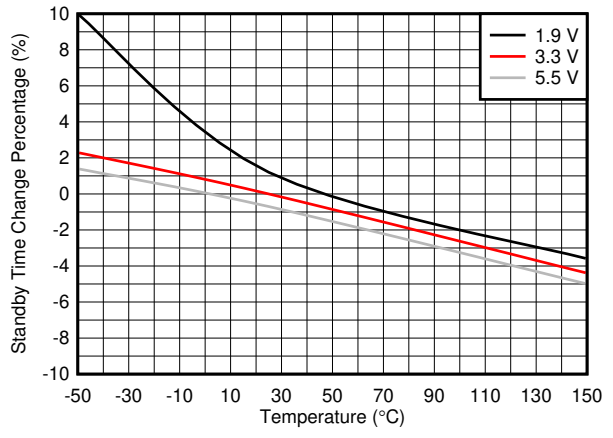


图 6-10. Standby Time vs Temperature

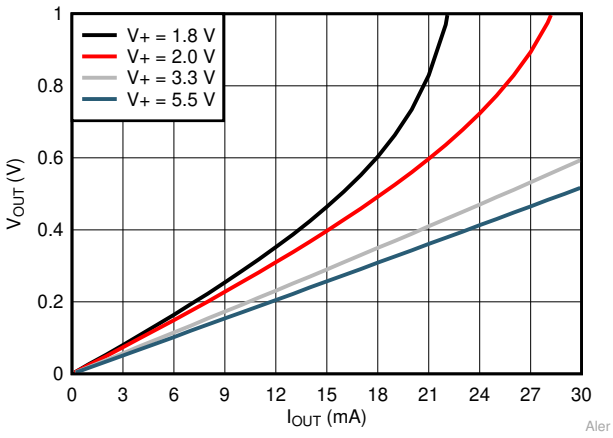
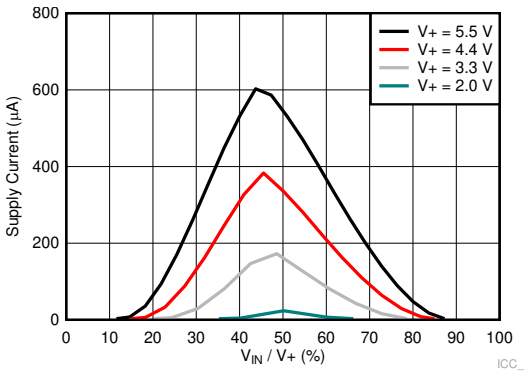


图 6-11. ALERT Pin Output Voltage vs Pin Sink Current

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6.9 Typical Characteristics (continued)

at T_A = 25°C, V+ = 3.3V, and measurement taken in oil bath (unless otherwise noted)



Input voltage of SCL, SDA, or ADD0 pin

图 6-12. Supply Current vs Input Cell Voltage

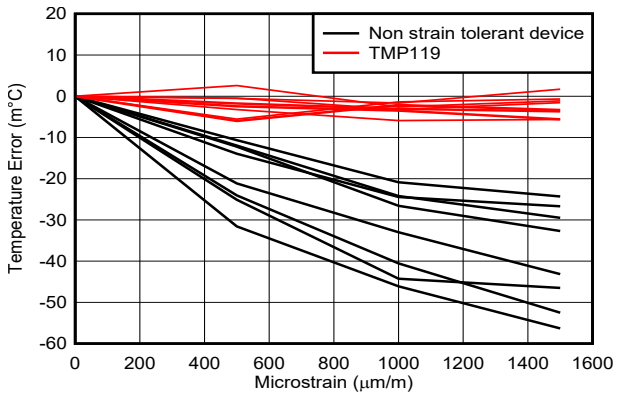


图 6-13. Temperature Error vs Microstrain

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7 Detailed Description

7.1 Overview

The TMP119 is a digital output temperature sensor designed for thermal-management and thermal-protection applications. The TMP119 is two-wire, SMBus, and I^{2}C interface-compatible. The device is specified over an ambient air operating temperature range of –55°C to 150°C. 图 7-1 shows a block diagram of the TMP119.

7.2 Functional Block Diagram

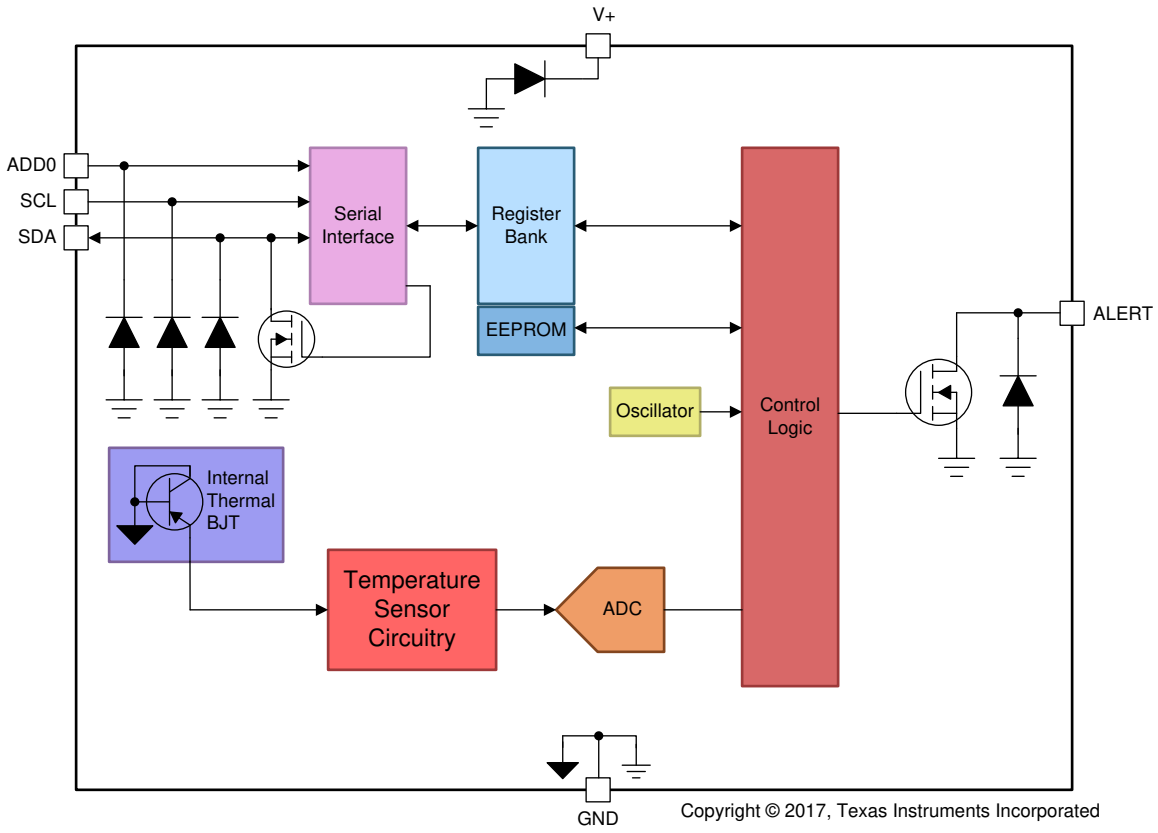


图 7-1. Internal Block Diagram

7.3 Feature Description

7.3.1 Power Up

After the supply voltage reaches within the operating range, the device requires 1.5ms to power up before conversions can begin. The device can be programmed to start up in shutdown mode as well. See the *EEPROM Programming* section for more information. The temperature register reads –256°C before the first conversion.

7.3.2 Averaging

Users can configure the device to report the average of multiple temperature conversions with the AVG[1:0] bits to reduce noise in the conversion results. When the TMP119 is configured to perform averaging with AVG set to 01, the device executes the configured number of conversions to eight. The device accumulates those conversion results and reports the average of all the collected results at the end of the process.

图 7-2 shows the total conversion cycle time trade-off when using the averaging mode to achieve this improvement in noise performance. Averaging will increase the average active current consumption due to increasing the active conversion time in a conversion cycle. For example a single active conversion typically takes 15.5ms, so if the device is configured to report an average of eight conversions, then the active conversion time is 124ms (15.5ms × 8). Use 方程式 1 to factor in this increase in active conversion time to accurately calculate the average current consumption of the device. The average current consumption of the device can be decreased by increasing the amount of time the device spends in standby period as compared to active conversion. Under the factory EEPROM settings, the device is configured to report an average of eight conversions with a conversion cycle time of 1 second by default.

Averaging can be used in both the continuous conversion mode and the one-shot mode.

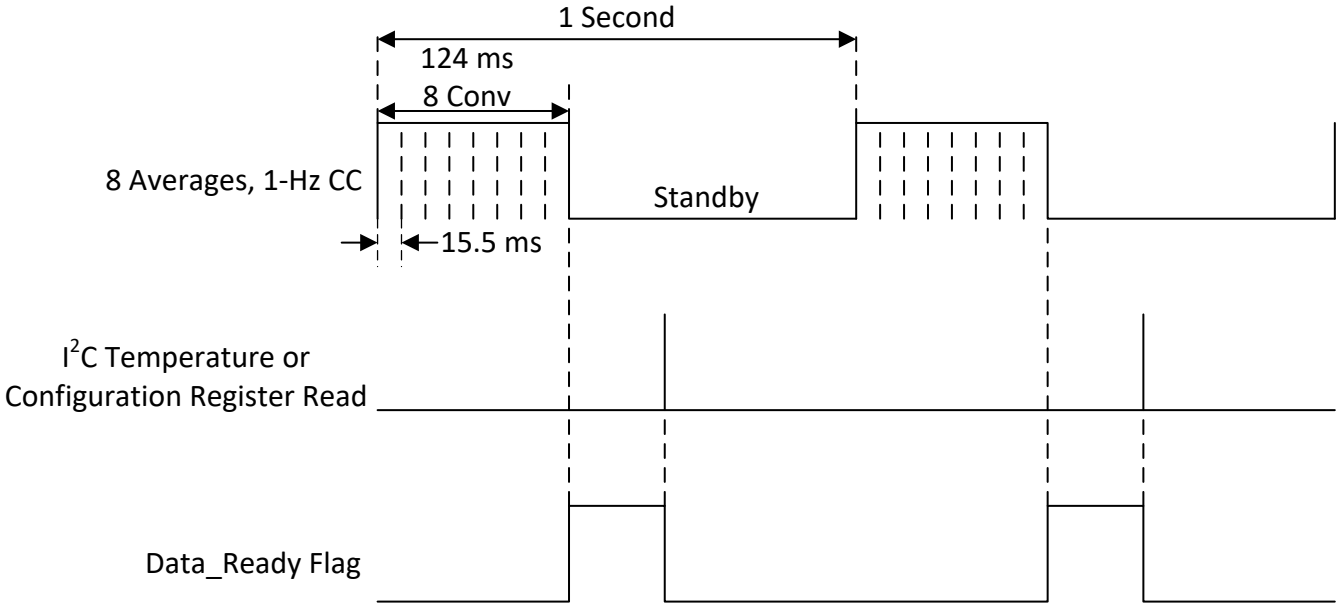


图 7-2. Averaging Timing Diagram

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7.3.3 Temperature Result and Limits

At the end of every conversion, the device updates the temperature register with the conversion result. The data in the result register is in 2's complement format, has a data width of 16 bits and a resolution of 7.8125m°C. 表 7-1 shows multiple examples of possible binary data that can be read from the temperature result register and the corresponding hexadecimal and temperature equivalents.

The TMP119 also has alert status flags and alert pin functionality that use the temperature limits stored in the low limit register and high limit register. The same data format used for the temperature result register is used for data written to the high and low limit registers.

表 7-1. 16-Bit Temperature Data Format

TEMPERATURE (°C)	TEMPERATURE REGISTER VALUE (0.0078125°C RESOLUTION)	
	BINARY	HEX
– 256	1000 0000 0000 0000	8000
– 25	1111 0011 1000 0000	F380
– 0.1250	1111 1111 1111 0000	FFF0
– 0.0078125	1111 1111 1111 1111	FFFF
0	0000 0000 0000 0000	0000
0.0078125	0000 0000 0000 0001	0001
0.1250	0000 0000 0001 0000	0010
1	0000 0000 1000 0000	0080
25	0000 1100 1000 0000	0C80
100	0011 0010 0000 0000	3200
255.9921	0111 1111 1111 1111	7FFF

7.3.4 Strain Tolerance

The TMP119 features internal strain tolerance that helps mitigate error resulting from strain developed in the DSBGA package from various common manufacturing areas, including but not limited to device solder, molding, under-fill, and board flex.

To demonstrate this capability, multiple TMP119 devices are soldered onto a rigid 62mil thick PCB, and tested under multiple flexing orientations, with pin 1 located both orthogonal and parallel to the applied microstrain examined during the test, measured through a strain gauge. The resultant temp error under this strain is measured against a known reference, and are recorded at increasing flex levels of the PCB. 图 7-3 demonstrates device distribution under these microstrain conditions. Several non-strain tolerant devices were also subjected to the same test to demonstrate the difference.

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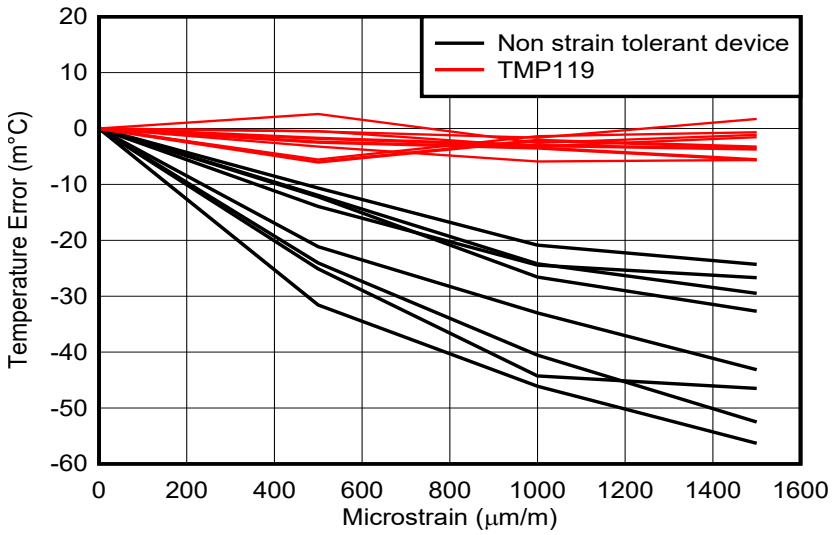


图 7-3. Strain Tolerance

7.4 Device Functional Modes

The TMP119 can be configured to operate in various conversion modes by using the MOD[1:0] bits. These modes provide flexibility to operate the device in the most power efficient way necessary for the intended application.

7.4.1 Continuous Conversion Mode

When the MOD[1:0] bits are set to 00 or 10 in the configuration register, the device operates in continuous conversion mode. The device continuously performs temperature conversions in this mode, as shown in 图 7-4, and updates the temperature result register at the end of every active conversion. The user can read the configuration register or the temperature result register to clear the Data_Ready flag. Therefore, the Data_Ready flag can be used to determine when the conversion completes so that an external controller can synchronize reading the result register with conversion result updates. The user can set the DR/nAlert_EN bit in the configuration register to monitor the state of the Data_Ready flag on the ALERT pin.

Every conversion cycle consists of an active conversion period followed by a standby period. The device typically consumes 135µA during active conversion and only 1.25µA during the low-power standby period. 图 7-4 shows a current consumption profile of a conversion cycle while in continuous current mode. The duration of the active conversion period and standby period can be configured using the CONV[2:0] and AVG[1:0] bits in the configuration register, thereby allowing the average current consumption of the device to be optimized based on the application requirements. Changing the conversion cycle period also affects the temperature result update rate because the temperature result register is updated at the end of every active conversion.

Use 方程式 1 to calculate the average current consumption of the device in continuous conversion mode.

$$\frac{(\text{Active Current Consumption} \times \text{Active Conversion Time}) + (\text{Standby Current Consumption} \times \text{Standby Time})}{\text{Conversion Cycle Time}} \quad (1)$$

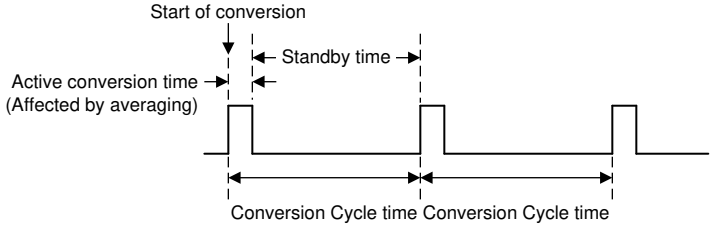


图 7-4. Conversion Cycle Timing Diagram

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7.4.2 Shutdown Mode (SD)

When the MOD[1:0] bits are set to 01 in the configuration register, the device instantly aborts the currently running conversion and enters a low-power shutdown mode. In this mode, the device powers down all active circuitry and can be used in conjunction with the OS mode to perform temperature conversions. Engineers can use the TMP119 for battery-operated systems and other low-power consumption applications because the device typically only consumes 250nA in SD mode.

7.4.3 One-Shot Mode (OS)

When the MOD[1:0] bits are set to 11 in the configuration register, the TMP119 can run a temperature conversion referred to as a one-shot conversion. After the device completes a one-shot conversion, the device goes to the low-power shutdown mode. A one-shot conversion cycle, unlike the continuous conversion mode, only consists of the active conversion time and no standby period. Thus, the duration of a one-shot conversion is only affected by the AVG bit settings. The CONV bits do not affect the duration of a one-shot conversion. 图 7-5 shows a timing diagram for this mode with an AVG setting of 00. At the end of a one-shot conversion, the Data_Ready and ALERT flag in the configuration register is set. The Data_Ready flag can be used to determine when the conversion completes. The user can perform an I^2C read on the configuration register or temperature result register to clear the Data_Ready flag. The user can also set the DR/nAlert_EN bit in the configuration register to monitor the state of the Data_Ready flag on the ALERT pin.

One-shot mode cannot be programmed to a default start-up mode. If the EEPROM is programmed to be in one-shot mode on start-up, the device will default to shutdown mode instead.

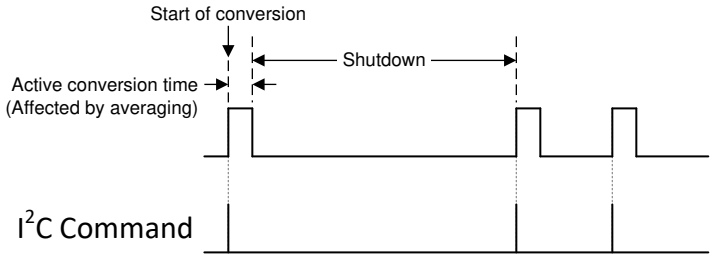


图 7-5. One-Shot Timing Diagram With AVG[1:0] = 00

7.4.4 Therm and Alert Modes

The built-in therm and alert functions of the TMP119 can alert the user if the temperature has crossed a certain temperature limit or if the device is within a certain temperature range. At the end of every conversion, including averaging, the TMP119 compares the converted temperature result to the values stored in the low limit register and high limit register. The device then either sets or clears the corresponding status flags in the configuration register, as described in this section.

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7.4.4.1 Alert Mode

When the T/nA bit in the configuration register is set to 0, the device is in alert mode. In this mode, the device compares the conversion result at the end of every conversion with the values in the low limit register and high limit register. If the temperature result exceeds the value in the high limit register, the HIGH_Alert status flag in the configuration register is set. If the temperature result is lower than the value in the low limit register, the LOW_Alert status flag in the configuration register is set. As shown in 图 7-6, the user can run an I^2C read from the configuration register to clear the status flags in alert mode.

When a user configures the device in alert mode, the mode affects the behavior of the ALERT pin. The device asserts the ALERT pin in this mode when either the HIGH_Alert or the LOW_Alert status flag is set, as shown in 图 7-6. The user can either run an I^2C read of the configuration register (which also clears the status flags) or run an SMBus alert response command (see the *SMBus Alert Function* section) to deassert the ALERT pin. The polarity of the ALERT pin can be changed by using the POL bit setting in the configuration register.

This mode effectively makes the device behave like a window limit detector. Thus this mode can be used in applications where detecting if the temperature goes outside of the specified range is necessary.

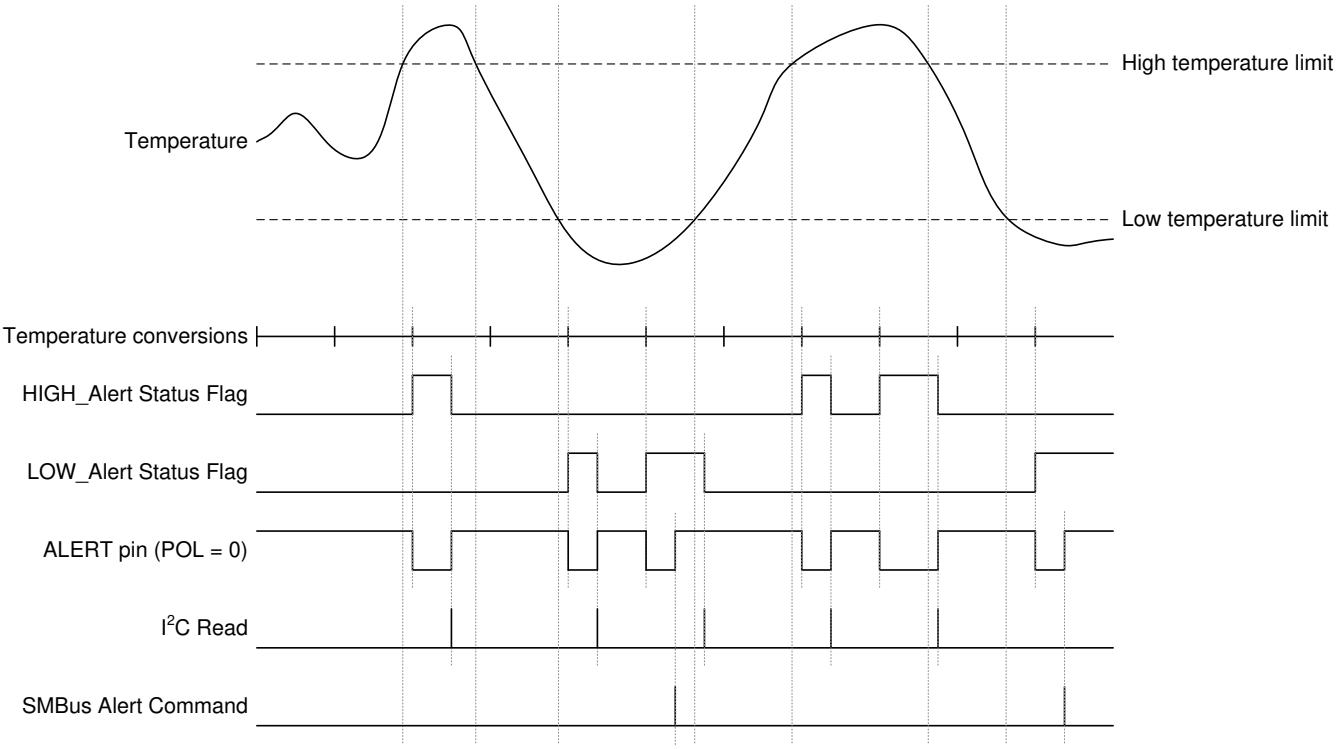


图 7-6. Alert Mode Timing Diagram

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7.4.4.2 Therm Mode

When the T/nA bit in the configuration register is set to 1, the device is in therm mode. In this mode, the device compares the conversion result at the end of every conversion with the values in the low limit register and high limit register and sets the HIGH_Alert status flag in the configuration register if the temperature exceeds the value in the high limit register. When set, the device clears the HIGH_Alert status flag if the conversion result goes below the value in the low limit register. Thus, the difference between the high and low limits effectively acts like a hysteresis. In this mode, the LOW_Alert status flag is disabled and always reads 0. Unlike the alert mode, I^2C reads of the configuration register do not affect the status bits. The HIGH_Alert status flag is only set or cleared at the end of conversions based on the value of the temperature result compared to the high and low limits.

As in alert mode, configuring the device in therm mode also affects the behavior of the ALERT pin. In this mode, the device asserts the ALERT pin if the HIGH_Alert status flag is set and deasserts the ALERT pin when the HIGH_Alert status flag is cleared. In therm mode, the ALERT pin cannot be cleared by performing an I^2C read of the configuration register or by performing an SMBus alert response command. As in alert mode, the polarity of the active state of the ALERT pin can be changed if the user adjusts the POL bit setting in the configuration register.

Thus, this mode effectively makes the device behave like a high-limit threshold detector. This mode can be used in applications where detecting if the temperature has gone above a desired threshold is necessary. 图 7-7 shows a timing diagram of this mode.

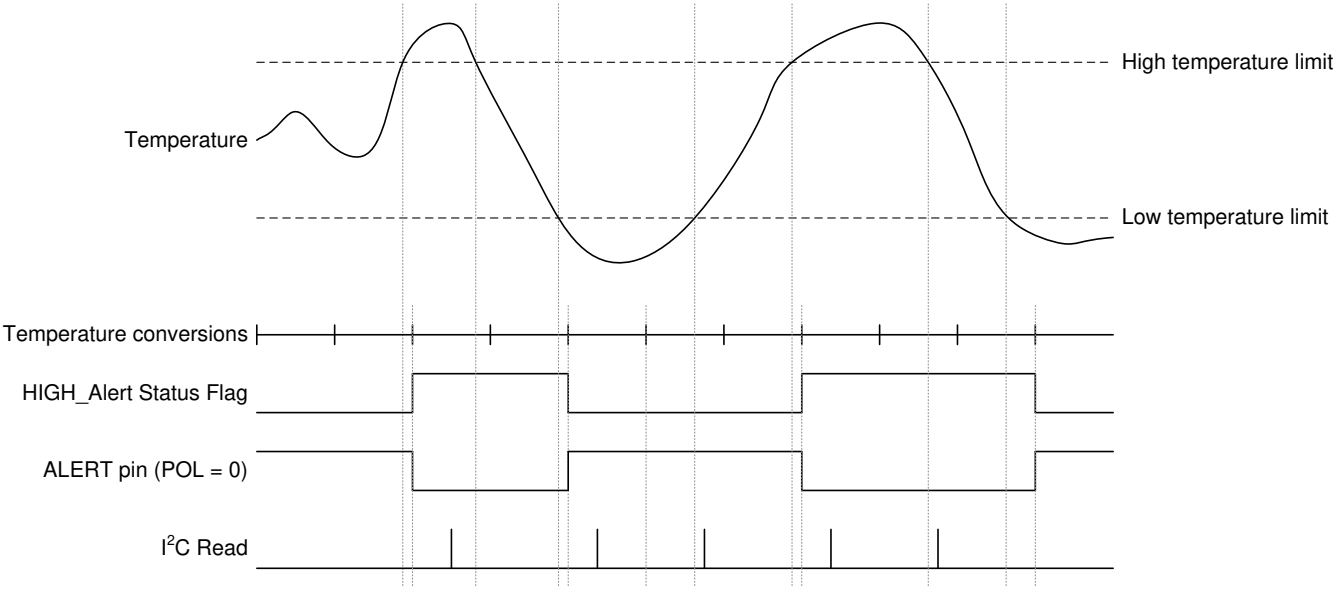


图 7-7. Therm Mode Timing Diagram

7.5 Programming

7.5.1 EEPROM Programming

7.5.1.1 EEPROM Overview

The device has a user-programmable EEPROM that can be used for two purposes:

- Storing power-on reset (POR) values of the high limit register, low limit register, conversion cycle time, averaging mode, conversion mode (continuous or shutdown mode), alert function mode (alert or therm mode), and alert polarity
- Storing four 16-bit locations for general-purpose use. See the EEPROM[4:1] registers for more information.

On reset, the device goes through a POR sequence that loads the values programmed in the EEPROM into the respective register map locations. This process takes approximately 1.5ms. When the power-up sequence is complete, the device starts operating in accordance to the configuration parameters that are loaded from the EEPROM. Any I^2C writes performed during this initial POR period to the limit registers or the configuration register are ignored. I^2C read transactions can still be performed with the device during the power-up period. While the POR sequence is being executed, the EEPROM_Busy status flag in the EEPROM unlock register is set.

During production, the EEPROM in the TMP119 is programmed with reset values as shown in 表 8-2. The *Programming the EEPROM* section describes how to change these values. A unique ID is also programmed in the general-purpose EEPROM locations during production. This unique ID is used to support NIST traceability. The TMP119 units are 100% tested on a production setup that is NIST traceable and verified with equipment that is calibrated to ISO/IEC 17025 accredited standards. Only reprogram the general-purpose EEPROM[4:1] locations if NIST traceability is not desired.

7.5.1.2 Programming the EEPROM

To prevent accidental programming, the EEPROM is locked by default. When locked, any I^2C writes to the register map locations are performed only on the volatile registers and not on the EEPROM.

图 7-8 shows a flow chart describing the EEPROM programming sequence. To program the EEPROM, first unlock the EEPROM by setting the EUN bit in the EEPROM unlock register. After the EEPROM is unlocked, any subsequent I^2C writes to the register map locations program a corresponding non-volatile memory location in the EEPROM. Programming a single location typically takes 7ms to complete and consumes 230µA. Do not perform any I^2C writes until programming is complete. During programming, the EEPROM_busy flag is set. Read this flag to monitor if the programming is complete. After programming the desired data, issue a general-call reset command to trigger a software reset. The programmed data from the EEPROM are then loaded to the corresponding register map locations as part of the reset sequence. This command also clears the EUN bit and automatically locks the EEPROM to prevent any further accidental programming. Avoid using the device to perform temperature conversions when the EEPROM is unlocked.

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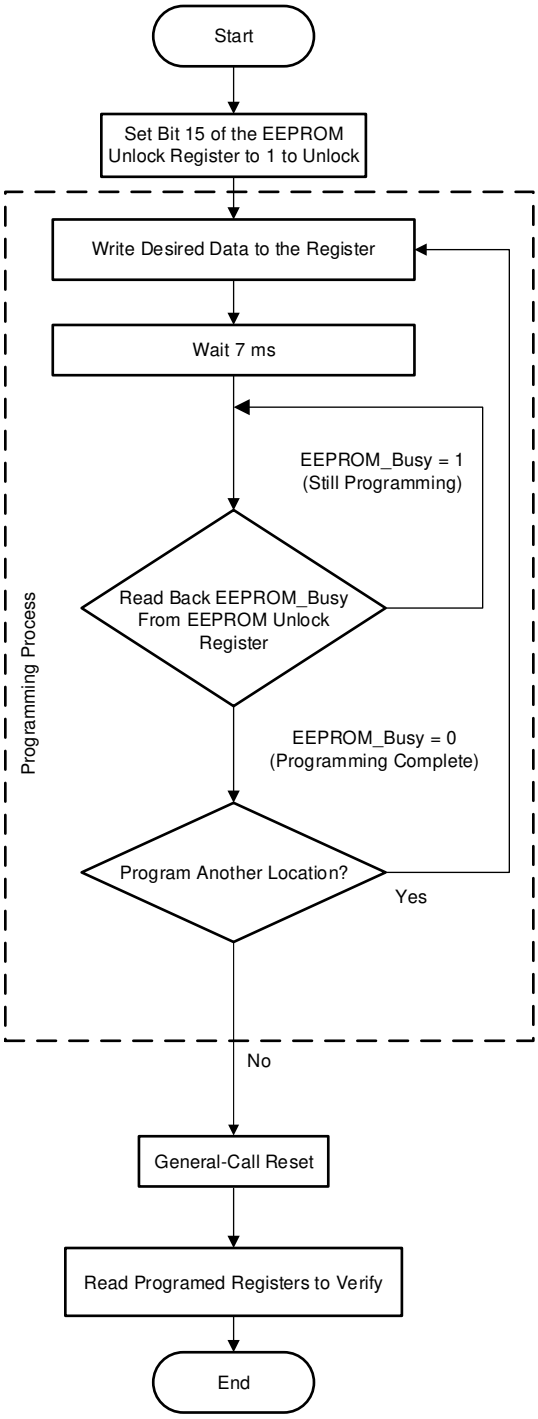


图 7-8. EEPROM Programming Sequence

7.5.2 Pointer Register

图 7-9 shows the internal register structure of the TMP119. The 8-bit pointer register of the device is used to address a given data register. The reset value is 00.

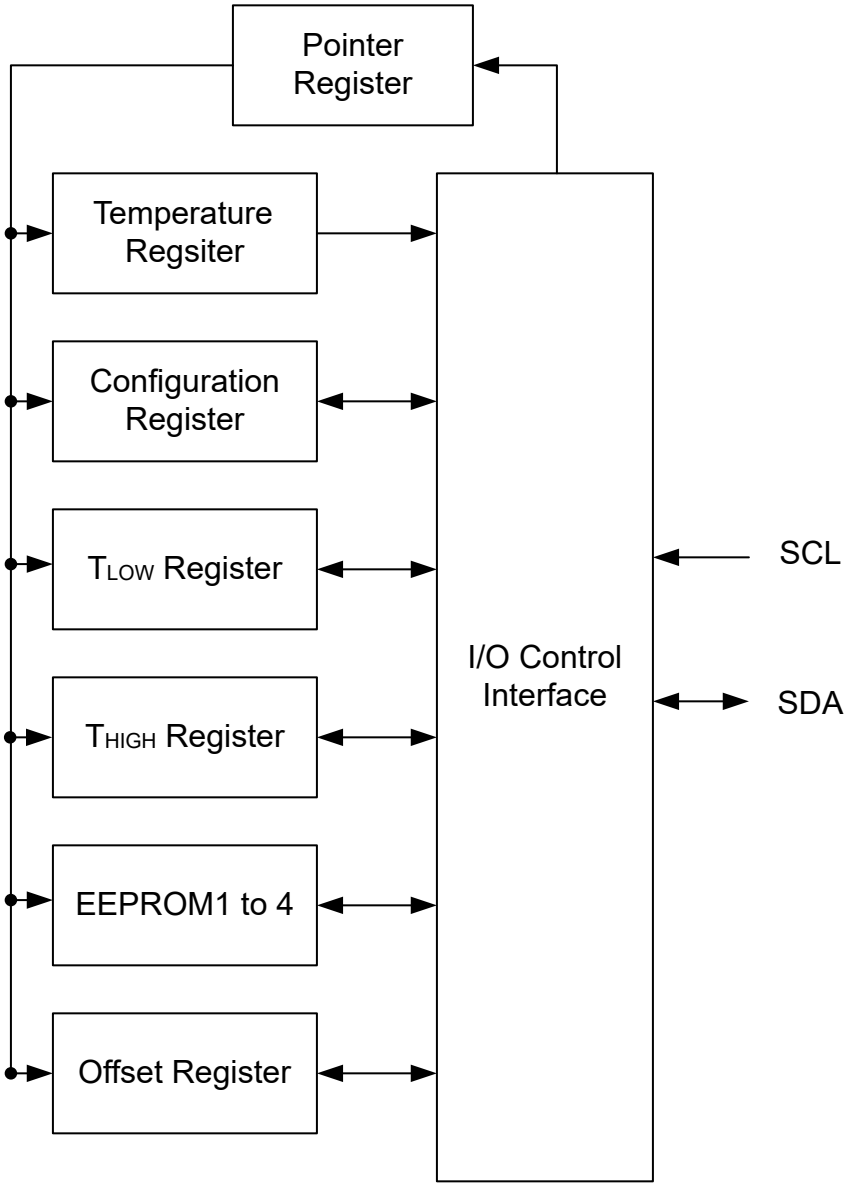


图 7-9. Internal Register Structures

7.5.3 I²C and SMBus Interface

7.5.3.1 Serial Interface

The TMP119 operates as a target device only on the two-wire, SMBus and I²C interface-compatible bus. Connections to the bus are made through the open-drain I/O lines, the SDA and SCL pins. The SDA and SCL pins feature integrated spike-suppression filters and Schmitt triggers to minimize the effects of input spikes and bus noise. The device supports the transmission protocol for fast (1kHz to 400kHz) mode. Register bytes are sent with the most significant byte first, followed by the least significant byte.

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7.5.3.1.1 Bus Overview

The device that initiates the transfer is called a *controller*, and the devices controlled by the controller are *targets*. The bus must be controlled by a controller device that generates the serial clock (SCL), controls the bus access, and generates the START and STOP conditions.

To address a specific device, a START condition is initiated, indicated by pulling the data line (SDA) from a high- to low-logic level when the SCL pin is high. All targets on the bus shift in the target address byte on the rising edge of the clock, and the last bit indicates whether a read or write operation is intended. During the ninth clock pulse, the addressed target generates an acknowledge and pulls the SDA pin low to respond to the controller.

A data transfer is then initiated and sent over eight clock pulses followed by an acknowledge bit. During the data transfer, the SDA pin must remain stable when the SCL pin is high because any change in the SDA pin when the SCL pin is high is interpreted as a START or STOP signal.

When all data are transferred, the controller generates a repeated START condition or a STOP condition.

- TMP119 will ignore any I^2C traffic until a START condition is observed
- TMP119 I^2C state machine resets every time the device sees a STOP condition
- For best precision, TI recommends to avoid I^2C communication during an active conversion

7.5.3.1.2 Serial Bus Address

To communicate with the TMP119, the controller must first address target devices through an address byte. The address byte has seven address bits and a read-write (R/W) bit that indicates the intent of executing a read or write operation.

The TMP119 features an address pin to allow up to four devices to be addressed on a single bus. 表 7-2 describes the pin logic levels used to properly connect up to four devices. *x* represents the read-write (R/ $\overline{W}$) bit.

表 7-2. Address Pin and Target Addresses

DEVICE TWO-WIRE ADDRESS	ADD0 PIN CONNECTION
1001000x	Ground
1001001x	V+
1001010x	SDA
1001011x	SCL

7.5.3.1.3 Writing and Reading Operation

The user can write a register address to the pointer register to access a particular register on the TMP119. The value for the pointer register is the first byte transferred after the target address byte with the R/ $\overline{W}$ bit low. Every write operation to the TMP119 requires a value for the pointer register.

When reading from the TMP119, the last value stored in the pointer register by a write operation is used to determine which register is read during a read operation. To change the register pointer for a read operation, a new value must be written to the pointer register. The user can issue an address byte with the R/ $\overline{W}$ bit low, followed by the pointer register byte to write a new value for the pointer register. No additional data is required. The controller can then generate a START condition and send the target address byte with the R/ $\overline{W}$ bit high to initiate the read command. See 图 7-11 for details of this sequence. If repeated reads from the same register are desired, it is not necessary to send the pointer register bytes continuously because the TMP119 retains the pointer register value until the value is changed by the next write operation.

Register bytes are sent with the most significant byte first, followed by the least significant byte.

7.5.3.1.4 Target Mode Operations

The TMP119 can operate as a target receiver or target transmitter. As a target device, the TMP119 never drives the SCL line.

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7.5.3.1.4.1 Target Receiver Mode

The first byte transmitted by the controller is the target address with the R/$\overline{W}$ bit low. The TMP119 then acknowledges reception of a valid address. The next byte transmitted by the controller is the pointer register. The TMP119 then acknowledges reception of the pointer register byte. The next byte(s) are written to the register addressed by the pointer register. The TMP119 acknowledges reception of each data byte. The controller can terminate data transfer by generating a START or STOP condition.

7.5.3.1.4.2 Target Transmitter Mode

The first byte transmitted by the controller is the target address with the R/$\overline{W}$ bit high. The target acknowledges reception of a valid target address. The next byte is transmitted by the target and is the most significant byte of the register indicated by the pointer register. The controller acknowledges reception of the data byte. The next byte transmitted by the target is the least significant byte. The controller acknowledges reception of the data byte. The controller can terminate data transfer by generating a *not-acknowledge* on reception of any data byte or by generating a START or STOP condition.

7.5.3.1.5 SMBus Alert Function

The TMP119 supports the SMBus alert function. When the ALERT pin is connected to an SMBus alert signal and a controller senses that an alert condition is present, the controller can send out an SMBus ALERT command (0001 1001) to the bus. If the ALERT pin is active, the device acknowledges the SMBus ALERT command and responds by returning the target address on the SDA line. The eighth bit (LSB) of the target address byte indicates if the alert condition is caused by the temperature exceeding $T_{(HIGH)}$ or falling below $T_{(LOW)}$. The LSB is high if the temperature is greater than $T_{(HIGH)}$, or low if the temperature is less than $T_{(LOW)}$. See 图 7-12 for details of this sequence.

In the event that the device with the lowest I^2C address in continuous conversion mode sees an alert, the controller can temporarily disable Alert mode in this device until all alerts in the system are cleared to prevent this device from blocking other devices with higher I^2C addresses from reporting to the controller.

If multiple devices on the bus respond to the SMBus ALERT command, arbitration during the target address portion of the SMBus ALERT command determines which device clears the alert status of that device. The device with the lowest two-wire address wins the arbitration. If the TMP119 wins the arbitration, the TMP119 ALERT pin becomes inactive at the completion of the SMBus ALERT command. If the TMP119 loses the arbitration, the TMP119 ALERT pin remains active.

7.5.3.1.6 General-Call Reset Function

The TMP119 responds to a two-wire, general-call address (0000 000) if the eighth bit is 0. The device acknowledges the general-call address and responds to commands in the second byte. If the second byte is 0000 0110, the TMP119 internal registers are reset to power-up values.

7.5.3.1.7 Timeout Function

The TMP119 resets the serial interface if the SCL line is held low by the controller or the SDA line is held low by the TMP119 for 35ms (typical) between a START and STOP condition. The TMP119 releases the SDA line if the SCL pin is pulled low and waits for a START condition from the host controller. To avoid activating the timeout function, maintain a communication speed of at least 1kHz for the SCL operating frequency.

7.5.3.1.8 Timing Diagrams

The TMP119 is two-wire, SMBus and I^2C interface-compatible. 图 7-10 to 图 7-13 show the various operations with the TMP119. Bus definitions are:

Bus Idle: Both SDA and SCL lines remain high.

Start Data Transfer: A change in the state of the SDA line from high to low when the SCL line is high defines a START condition. Each data transfer is initiated with a START condition.

Stop Data Transfer: A change in the state of the SDA line from low to high when the SCL line is high defines a STOP condition. Each data transfer is terminated with a repeated START or STOP condition.

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Data Transfer: The number of data bytes transferred between a START and a STOP condition is not limited and is determined by the controller device.

Acknowledge: Each receiving device, when addressed, is obliged to generate an acknowledge bit. A device that acknowledges must pull down the SDA line during the acknowledge clock pulse in such a way that the SDA line is stable low during the high period of the acknowledge clock pulse. The user must take setup and hold times into account. On a controller receive, the termination of the data transfer can be signaled by the controller generating a *not-acknowledge* (1) on the last byte transmitted by the target.

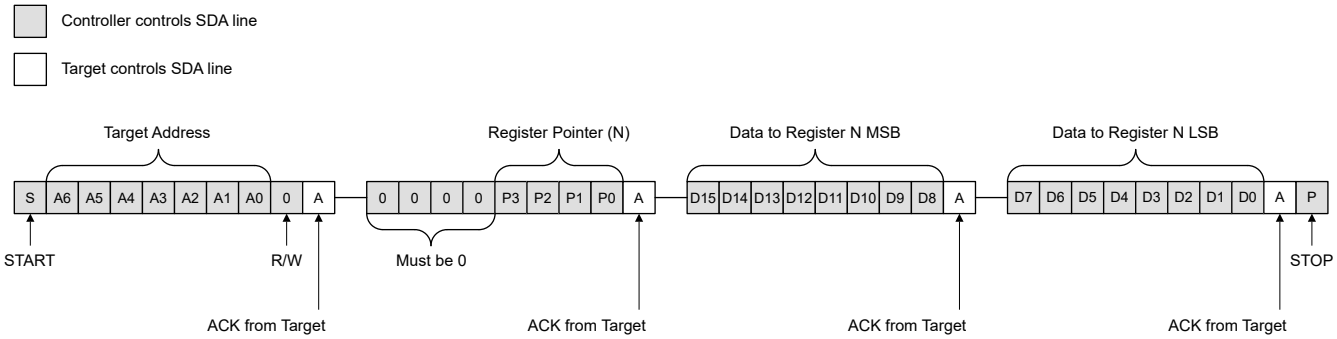


图 7-10. Write Word Command Timing Diagram

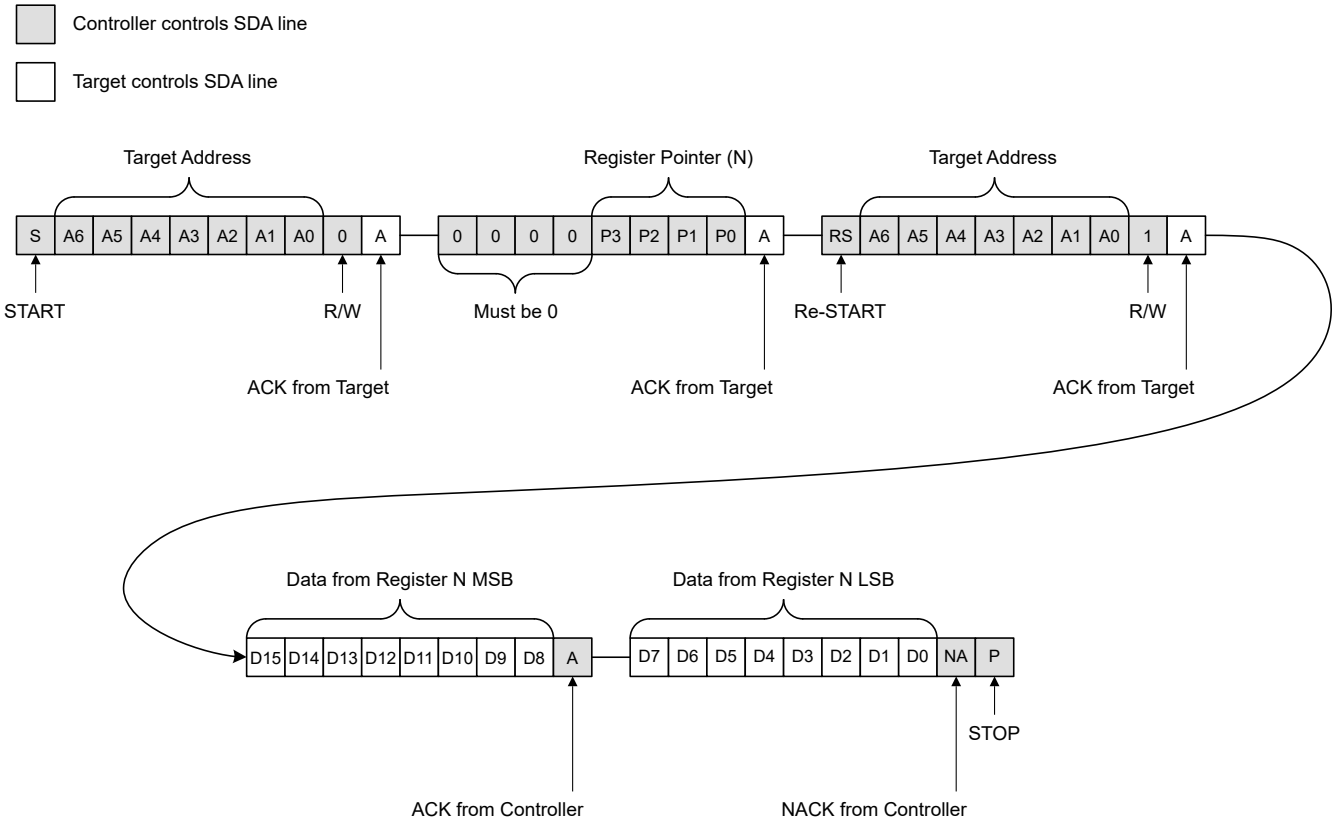


图 7-11. Read Word Command Timing Diagram

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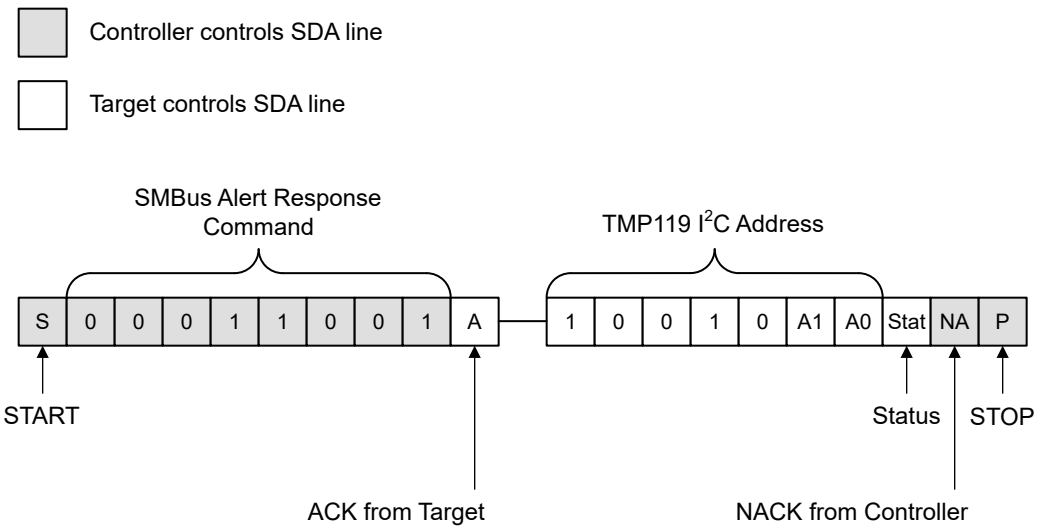


图 7-12. SMBus ALERT Timing Diagram

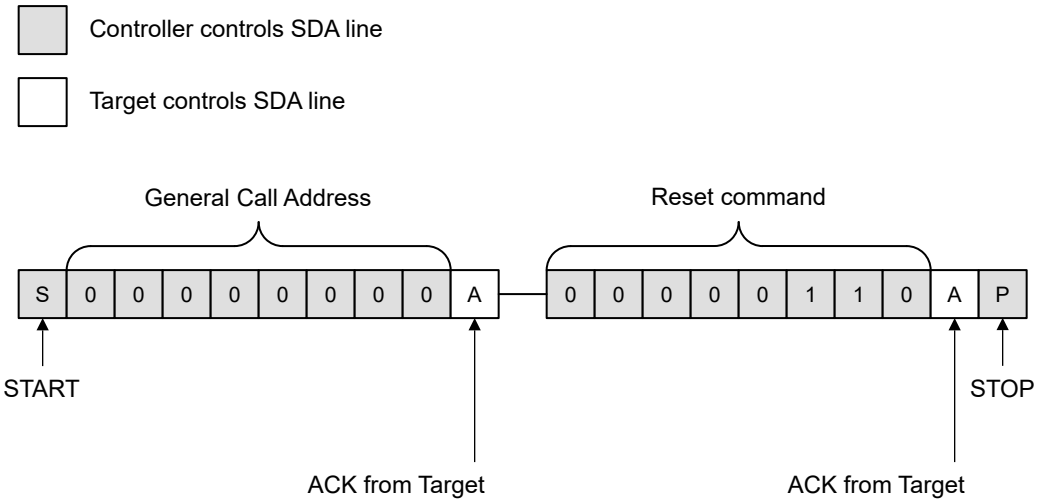


图 7-13. General-Call Reset Command Timing Diagram

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8 Application and Implementation

备注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI’s customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The TMP119 is used to measure the temperature of the board location where the device is mounted. The programmable address options allow up to four locations on the board to be monitored on a single serial bus. For more information, refer to the related *Considerations for Measuring Ambient Air Temperature* (SNOA966), *Replacing resistance temperature detectors with the TMP116 temp sensor* (SNOA969), and *Temperature sensors: PCB guidelines for surface mount devices* (SNOA967) application reports on ti.com.

8.1.1 C-Code Decoding Temperature Data

The TMP119 temperature registers use a 16-bit format. Temperature data is represented by a 16-bit 2's complement word with a Least Significant Bit (LSB) equal to 0.0078125°C. The temperature output of the TMP119 has a range of -256°C to 255°C. The fractional values are included in the temperature readings, which can be denoted using Q notation, a simple way to represent the length of the fractional portion of the value. 2's Compliment is employed to describe negative temperatures. C code can easily convert the 2's Compliment data when the data is typecast into the correct signed data type.

图 8-1. Encoding Parameters

Parameter	Value
Bits	16
Q	7
Resolution	0.0078125
Range (+)	255.9921875
Range (-)	-256
25˚C	0xC80

表 8-1. 16-Bit Q Notation Bit Weights

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Sign	128	64	32	16	8	4	2	1	0.5	0.25	0.125	0.0625	0.03125	0.015625	0.0078125
-256	128	64	32	16	8	4	2	1	1/2	1/4	1/8	1/16	1/32	1/64	1/128
-2^8	2^7	2^6	2^5	2^4	2^3	2^2	2^1	2^0	2^{-1}	2^{-2}	2^{-3}	2^{-4}	2^{-5}	2^{-6}	2^{-7}

```
C Code Examples:
/* 16-bit format will have 0 bits discarded by right shift
q7 is 0.0078125 resolution
the following bytes represent 24.5C */
uint8_t byte1 = 0xC;
uint8_t byte2 = 0x40;
float f = ((int8_t) byte1 << 8 | byte2) * 0.0078125f;
int mC = ((int8_t) byte1 << 8 | byte2) * 1000 >> 7;
int C = ((int8_t) byte1 << 8 | byte2) >> 7;
```

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8.2 Typical Application

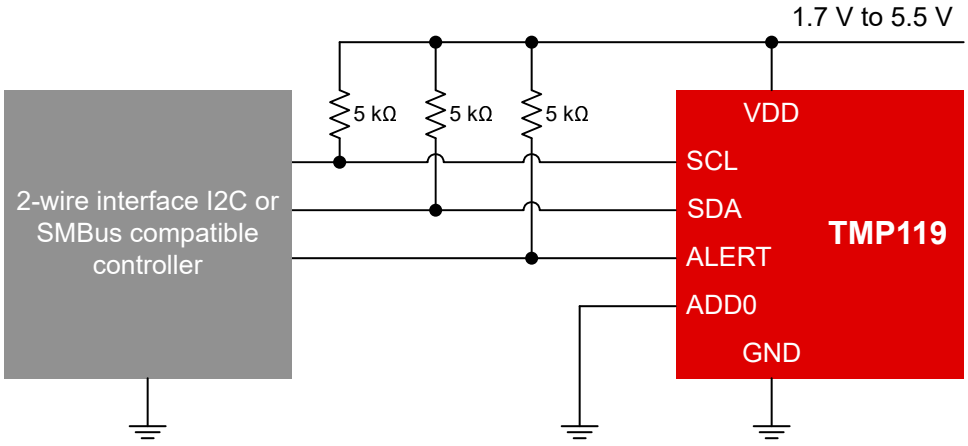


图 8-2. Typical Connections

8.2.1 Design Requirements

The TMP119 operates only as a target device and communicates with the host through the I^{2}C-compatible serial interface. SCL is the input pin, SDA is a bidirectional pin, and ALERT is the output. The TMP119 requires a pullup resistor on the SDA, and ALERT pins. The recommended value for the pullup resistors is 5kΩ. In some applications, the pullup resistor can be lower or higher than 5kΩ. A 0.1µF bypass capacitor is recommended to be connected between V+ and GND. An SCL pullup resistor is required if the system microprocessor SCL pin is open-drain. Use a ceramic capacitor type with a temperature rating that matches the operating range of the application, and place the capacitor as close as possible to the V+ pin of the TMP119. The ADD0 pin can be connected directly to GND, V+, SDA and SCL for address selection of four possible unique target ID addresses. 表 7-1 explains the addressing scheme. The ALERT output pin can be connected to a microcontroller interrupt that triggers an event that occurred when the temperature limit exceeds the programmable value in registers 02h and 03h. The ALERT pin can be left floating or connected to ground when not in use.

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8.2.2 Detailed Design Procedure

8.2.2.1 Noise and Averaging

The device temperature sampling distribution (with averaging disabled) covers an area of approximately six neighboring codes. The noise area of the six codes remains the same at full supply and full temperature range with a standard deviation of approximately 1 LSB. The device provides an averaging tool for 1, 8, 32, or 64 conversions. As shown in 图 6-5, the 8-sample averaging reduces the internal noise distribution to a theoretical minimum of two LSBs. This averaging means that if the system temperature slowly changes and the supply voltage is stable, then the 8-sample averaging can be enough to neutralize the device noise and provide stable temperature readings. However, if the system environment is noisy (such as when measuring air flow temperatures, power supply fluctuations, intensive communication on a serial bus, and so forth), then higher averaging numbers are recommended to be used.

8.2.2.2 Self-Heating Effect (SHE)

During ADC conversion, some power is dissipated that heats the device despite the small power consumption of the TMP119. Consider the self-heating effect (SHE) for certain precise measurements. 图 8-3 shows the device SHE in still air at 25°C after the supply is switched on. The device package is soldered to the 11mm × 20mm × 0.7mm size coupon board. The board is placed horizontally, with the device on top. The TMP119 is in continuous conversion mode with 64 sampling averaging and zero conversion cycle time. There is no digital bus activity aside from reading temperature data one time each second. As shown in 图 8-3, the SHE stabilization time in still air is greater when the device dissipates more power.

The SHE drift is strongly proportional to the device dissipated power. The SHE drift is also proportional to the device temperature because the consumption current with the same supply voltage increases with temperature. 图 8-4 shows the SHE drifts versus temperature and dissipated power at 25 °C for the same coupon board and the same conditions described previously.

To estimate the SHE for similar size boards, calculate the device consumption power for 25°C and use the corresponding power line shown in 图 8-4.

The following methods can reduce the SHE:

- System calibration removes not only the self-heating error and power-supply rejection ratio (PSRR) effect but also compensates the temperature shift caused by the thermal resistance between the device and the measured object.
- If practical, use the device one-shot mode. If continuous conversion is needed, use the conversion cycle mode with significant standby time. For example, in most cases an 8-sample averaging (125ms) with a 1-second conversion cycle provides enough time for the device to cool down to the environment temperature and removes the SHE.
- Use the minimal acceptable power supply voltage.
- Use a printed-circuit board (PCB) layout that provides minimal thermal resistance to the device.
- Avoid using small-value pullup resistors on the SDA and ALERT pins. Instead, use pullup resistors larger than 2kΩ.
- Ensure that the SCL and SDA signal levels remain below 10% or above 90% of the device supply voltage.
- Avoid heavy bypass traffic on the data line. Communication to other devices on the same data line increases the supply current even if the device is in SD mode.
- Use the highest available communication speed.

8.2.2.3 Synchronized Temperature Measurements

When four temperature measurements are needed in four different places simultaneously, triggering a reset is recommended. In this method, four devices are programed with control registers set to CC mode with a conversion cycle time of 16s. All four devices are connected to same two-wire bus with four different bus addresses. The bus general-call reset command is issued by the controller. This command triggers all devices to reset (which takes approximately 1.5ms) and triggers a simultaneous temperature sampling according to configuration registers setting. The controller has 16 seconds to read data from the devices.

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8.2.3 Application Curves

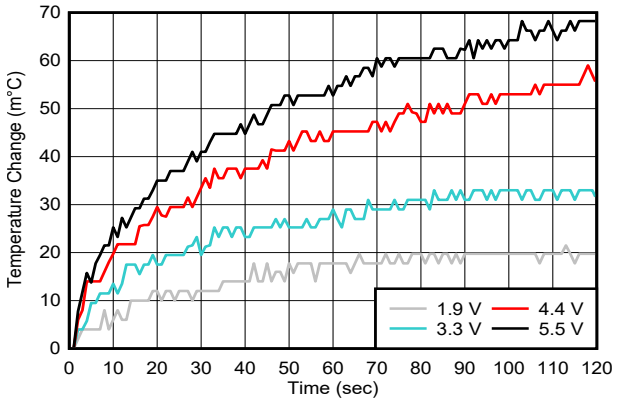


图 8-3. Self-Heating in Still Air vs Temperature and Dissipated Power

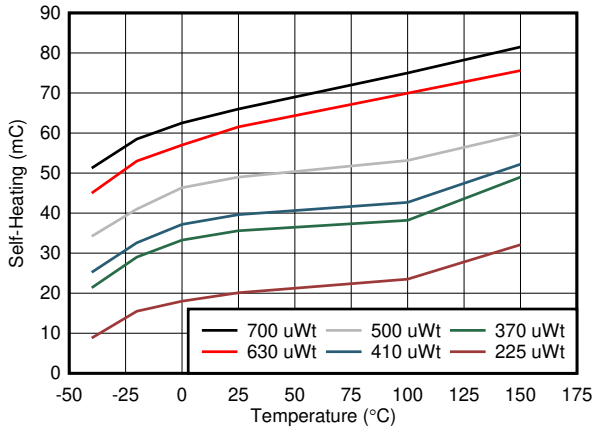


图 8-4. Self-Heating in Still Air vs Temperature and Dissipated Power at 25°C

8.3 Power Supply Recommendations

The TMP119 operates on a power-supply range from 1.7V to 5.5V. A power-supply bypass capacitor is required, which must be placed as close to the supply and ground pins of the device as possible. A recommended value for this supply bypass capacitor is 100nF. Applications with noisy or high-impedance power supplies may require additional decoupling capacitors to reject power-supply noise.

8.4 Layout

8.4.1 Layout Guidelines

For more information on board layout, refer to the related *Precise temperature measurements with TMP116 and TMP117* (SNOA986) and *Wearable temperature-sensing layout considerations optimized for thermal response* (SNIA021) application reports on ti.com.

Place the power-supply bypass capacitor as close as possible to the supply and ground pins. The recommended value of this bypass capacitor is 0.1 µF. In some cases, the pullup resistor can be the heat source, therefore, maintain some distance between the resistor and the device.

1. If the device is used to measure solid surface temperature:
   - Use PCB with minimal thickness.
   - Prevent PCB bending which can create a mechanical stress to package.
   - Cover bottom of the PCB with copper plane.
   - Remove bottom solder mask and cover exposed copper with gold layer if possible.
   - Use thermal conductive paste between PCB and object surface.
   - If PCB has unused internal layers, extend these layers under the sensor.
   - Minimize amount of copper wires on top of the board.
   - To minimize temperature “leakage” to surrounding air locate sensor in place with minimal air movement. Horizontal surfaces are preferable.
   - To minimize temperature offset due to “leakage” to surrounding air cover sensor with thermo isolating foam, tape or at least cover with a stain.
2. If the device is used to measure moving air temperature:
   - Because moving air temperature usually has a lot of fluctuations the PCB increased thermal mass reduces measurement noise.
   - Use a PCB with thicker copper layers if possible.
   - Cover both side of unused board space with copper layer.

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- Place PCB vertically along air flow.

3. If the device is used to measure still air temperature:
   - Miniaturize the board to reduce thermal mass. Smaller thermal mass results in faster thermal response.
   - Remove the top solder mask.
   - To prevent oxidation, cover any exposed copper with solder paste.
   - Thermal isolation is required to avoid thermal coupling from heat source components through the PCB.
   - Avoid running the copper plane underneath the temperature sensor.
   - Maximize the air gap between the sensor and the surrounding copper areas (anti-etch), especially when close to the heat source.
   - Create a PCB cutout between sensor and other circuits. Leave a narrow channel away from heat source components as a routing bridge into the island.
   - If the heat source is top side, avoid running traces on top; instead, route all signals on the bottom side.
   - Place the board vertically to improve air flow and to reduce dust collection.

8.4.2 Layout Example

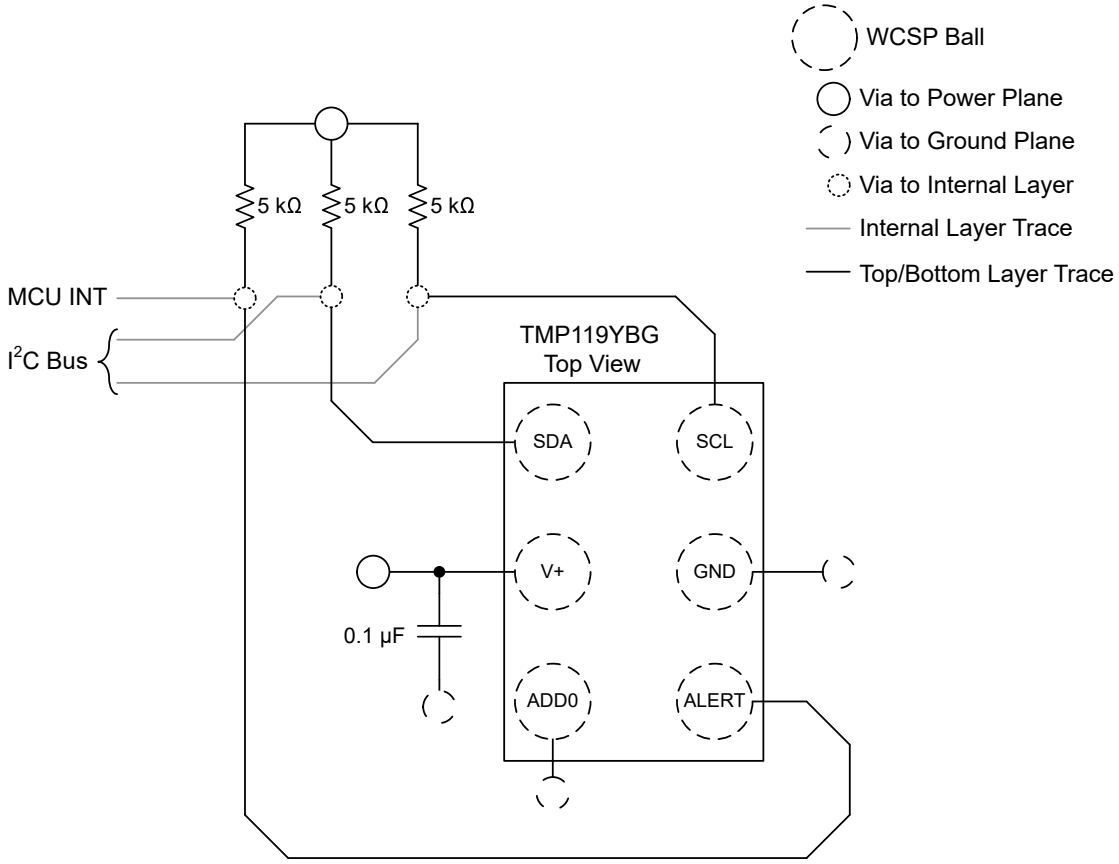


图 8-5. YBG Layout Recommendation

8.5 Register Map

表 8-2. TMP119 Register Map

ADDRESS	TYPE	RESET	ACRONYM	REGISTER NAME	SECTION
00h	R	8000h	Temp_Result	Temperature result register	Go
01h	R/W	0220h(1)	Configuration	Configuration register	Go
02h	R/W	6000h(1)	THigh_Limit	Temperature high limit register	Go
03h	R/W	8000h(1)	TLow_Limit	Temperature low limit register	Go
04h	R/W	0000h	EEPROM_UL	EEPROM unlock register	Go
05h	R/W	xxxxh(1)	EEPROM1	EEPROM1 register	Go
06h	R/W	xxxxh(1)	EEPROM2	EEPROM2 register	Go
07h	R/W	0000h(1)	Temp_Offset	Temperature offset register	Go
08h	R/W	xxxxh(1)	EEPROM3	EEPROM3 register	Go
0Fh	R	0117h	Device_ID	Device ID register	Go

(1) This value is stored in Electrically-Erasable, Programmable Read-Only Memory (EEPROM) during device manufacturing. The device reset value can be changed by writing the relevant code in the EEPROM cells (see the *EEPROM Overview* section).

表 8-3. TMP119 Access Type Codes

Access Type	Code	Description
Read Type		
R	R	Read
RC	R C	Read to Clear
Write Type		
W	W	Write
Reset or Default Value		
-n		Value after reset or the default value

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8.5.1 Register Descriptions

8.5.2 Temperature Register (address = 00h) [default reset = 8000h]

This register is a 16-bit, read-only register that stores the output of the most recent conversion. One LSB equals 7.8125m°C. Data are represented in binary 2's complement format. Following a reset, the temperature register reads –256°C until the first conversion, including averaging, is complete. See the *Power Up* section for more information.

Return to Register Map.

图 8-6. Temperature Register

15	14	13	12	11	10	9	8
T15	T14	T13	T12	T11	T10	T9	T8
R-1	R-0	R-0	R-0	R-0	R-0	R-0	R-0
7	6	5	4	3	2	1	0
T7	T6	T5	T4	T3	T2	T1	T0
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0

表 8-4. Temperature Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:0	T[15:0]	R	8000h	16-bit, read-only register that stores the most recent temperature conversion results in 2's complement format.

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8.5.3 Configuration Register (address = 01h) [factory default reset = 0220h]

Return to Register Map.

图 8-7. Configuration Register

15	14	13	12	11	10	9	8
HIGH_Alert	LOW_Alert	Data_Ready	EEPROM_Busy	MOD1(2)	MOD0(1)	CONV2(1)	CONV1(1)
R-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-1	R/W-0
7	6	5	4	3	2	1	0
CONV0(1)	AVG1(1)	AVG0(1)	T/nA(1)	POL(1)	DR/Alert(1)	Soft_Reset	—
R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R-0	R-0

表 8-5. Configuration Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15	HIGH_Alert	R	0	High Alert flag: 1: Set when the conversion result is higher than the high limit 0: Cleared on read of configuration register Therm mode: 1: Set when the conversion result is higher than the therm limit 0: Cleared when the conversion result is lower than the hysteresis
14	LOW_Alert	R	0	Low Alert flag: 1: Set when the conversion result is lower than the low limit 0: Cleared when the configuration register is read Therm mode: Always set to 0
13	Data_Ready	R	0	Data ready flag. This flag indicates that the conversion is complete and the temperature register can be read. Every time the temperature register or configuration register is read, this bit is cleared. This bit is set at the end of the conversion when the temperature register is updated. Data ready can be monitored on the ALERT pin by setting bit 2 of the configuration register.
12	EEPROM_Busy	R	0	EEPROM busy flag. The value of the flag indicates that the EEPROM is busy during programming or power-up.
11:10	MOD[1:0]	R/W	0	Set conversion mode. 00: Continuous conversion (CC) 01: Shutdown (SD) 10: Continuous conversion (CC), Same as 00 (reads back = 00) 11: One-shot conversion (OS)
9:7	CONV[2:0]	R/W	100	Conversion cycle bit. See 表 8-6 for the standby time between conversions.
6:5	AVG[1:0]	R/W	01	Conversion averaging modes. Determines the number of conversion results that are collected and averaged before updating the temperature register. The average is an accumulated average and not a running average. 00: No averaging 01: 8 Averaged conversions 10: 32 averaged conversions 11: 64 averaged conversions
4	T/nA	R/W	0	Therm/alert mode select. 1: Therm mode 0: Alert mode
3	POL	R/W	0	ALERT pin polarity bit. 1: Active high 0: Active low
2	DR/Alert	R/W	0	ALERT pin select bit. 1: ALERT pin reflects the status of the data ready flag 0: ALERT pin reflects the status of the alert flags

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表 8-5. Configuration Register Field Descriptions（续）

BIT	FIELD	TYPE	RESET	DESCRIPTION
1	Soft_Reset	R/W	0	Software reset bit. When set to 1, this bit triggers a software reset with a duration of 2ms This bit will always read back 0
0	—	R	0	Not used

(1) These bits can be stored in EEPROM. The factory setting for this register is 0220.
(2) The MOD1 bit cannot be stored in EEPROM. The device can only be programmed to start up in shutdown mode or continuous conversion mode.

表 8-6. Conversion Cycle Time in CC Mode

CONV[2:0]	AVG[1:0] = 00	AVG[1:0] = 01	AVG[1:0] = 10	AVG[1:0] = 11
000	15.5ms	125ms	500ms	1s
001	125ms	125ms	500ms	1s
010	250ms	250ms	500ms	1s
011	500ms	500ms	500ms	1s
100	1s	1s	1s	1s
101	4s	4s	4s	4s
110	8s	8s	8s	8s
111	16s	16s	16s	16s

If the time to complete the conversions needed for a given averaging setting is higher than the conversion setting cycle time, there will be no stand by time in the conversion cycle.

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8.5.4 High Limit Register (address = 02h) [Factory default reset = 6000h]

This register is a 16-bit, read/write register that stores the high limit for comparison with the temperature result. One LSB equals 7.8125m°C. The range of the register is ±256°C. Negative numbers are represented in binary 2's complement format. Following power-up or a general-call reset, the high-limit register is loaded with the stored value from the EEPROM. The factory default reset value is 6000h.

Return to Register Map.

图 8-8. High Limit Register

15	14	13	12	11	10	9	8
H15	H14	H13	H12	H11	H10	H9	H8
R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
7	6	5	4	3	2	1	0
H7	H6	H5	H4	H3	H2	H1	H0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 8-7. High Limit Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:0	H[15:0]	R/W	6000h	16-bit, read/write register that stores the high limit for comparison with the temperature result.

8.5.5 Low Limit Register (address = 03h) [Factory default reset = 8000h]

This register is configured as a 16-bit, read/write register that stores the low limit for comparison with the temperature result. One LSB equals 7.8125m°C. The range of the register is ±256°C. Negative numbers are represented in binary 2's complement format. The data format is the same as the temperature register. Following power-up or reset, the low-limit register is loaded with the stored value from the EEPROM. The factory default reset value is 8000h.

Return to Register Map.

图 8-9. Low Limit Register

15	14	13	12	11	10	9	8
L15	L14	L13	L12	L11	L10	L9	L8
R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
7	6	5	4	3	2	1	0
L7	L6	L5	L4	L3	L2	L1	L0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 8-8. Low Limit Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:0	L[15:0]	R/W	8000h	16-bit, read/write register that stores the low limit for comparison with the temperature result.

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8.5.6 EEPROM Unlock Register (address = 04h) [reset = 0000h]

Return to Register Map.

图 8-10. EEPROM Unlock Register

15	14	13	12	11	10	9	8
EUN	EEPROM_Busy	—	—	—	—	—	—
R/W-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
7	6	5	4	3	2	1	0
—	—	—	—	—	—	—	—
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0

表 8-9. EEPROM Unlock Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15	EUN	R/W	0	EEPROM unlock. 0: EEPROM is locked for programming: writes to all EEPROM addresses (such as configuration, limits, and EEPROM locations 1-4) are written to registers in digital logic and are not programmed in the EEPROM 1: EEPROM unlocked for programming: any writes to programmable registers program the respective location in the EEPROM
14	EEPROM_Busy	R	0	EEPROM busy. This flag is the mirror of the EEPROM busy flag (bit 12) in the configuration register. 0: Indicates that the EEPROM is ready, which means that the EEPROM has finished the last transaction and is ready to accept new commands 1: Indicates that the EEPROM is busy, which means that the EEPROM is currently completing a programming operation or performing power-up on reset load
13:0	—	R	0	Not used

8.5.7 EEPROM1 Register (address = 05h) [reset = XXXXh]

The EEPROM1 register is a 16-bit register that be used as a scratch pad by the customer to store general-purpose data. This register has a corresponding EEPROM location. Writes to this address when the EEPROM is locked write data into the register and not to the EEPROM. Writes to this register when the EEPROM is unlocked causes the corresponding EEPROM location to be programmed. See the *Programming the EEPROM* section for more information. EEPROM[4:1] are preprogrammed during manufacturing with the unique ID that can be overwritten. To support NIST traceability do not delete or reprogram the EEPROM[1] register.

Return to Register Map.

图 8-11. EEPROM1 Register

15	14	13	12	11	10	9	8
D15	D14	D13	D12	D11	D10	D9	D8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x

表 8-10. EEPROM1 Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:0	D[15:0]	R/W	xxxxh	This 16-bit register can be used as a scratch pad. To support NIST traceability do not delete or re-program this register.

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8.5.8 EEPROM2 Register (address = 06h) [reset = 0000h]

This register function the same as the EEPROM1 register.

Return to Register Map.

图 8-12. EEPROM2 Register

15	14	13	12	11	10	9	8
D15	D14	D13	D12	D11	D10	D9	D8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x

表 8-11. EEPROM2 Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:0	D[15:0]	R/W	xxxxh	This 16-bit register can be used as a scratch pad.

8.5.9 Temperature Offset Register (address = 07h) [reset = 0000h]

Use this 16-bit register as a user-defined temperature offset register during system calibration. The offset will be added to the temperature result after linearization. This register has a same resolution of 7.8125m°C and the same range of ±256°C as the temperature result register. The data format is the same as the temperature register. If the added result is out of boundary, then the temperature result will show as the maximum or minimum value.

Return to Register Map.

图 8-13. Temperature Offset Register

15	14	13	12	11	10	9	8
D15	D14	D13	D12	D11	D10	D9	D8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

表 8-12. Temperature Offset Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:0	D[15:0]	R/W	0	Temperature offset data from system calibration.

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8.5.10 EEPROM3 Register (address = 08h) [reset = xxxxh]

This register function is the same as the EEPROM1 register. To support NIST traceability, do not delete or reprogram the EEPROM[1] register.

Return to Register Map.

图 8-14. EEPROM3 Register

15	14	13	12	11	10	9	8
D15	D14	D13	D12	D11	D10	D9	D8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x

表 8-13. EEPROM3 Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:0	D[15:0]	R/W	xxxxh	This 16-bit register is used as a scratch pad. To support NIST traceability, do not delete or re-program this register.

8.5.11 Device ID Register (address = 0Fh) [reset = 2117h]

This read-only register indicates the device ID.

Return to Register Map.

图 8-15. Device ID Register

15	14	13	12	11	10	9	8
Rev3	Rev2	Rev1	Rev0	DID11	DID10	DID9	DID8
R-0	R-0	R-1	R-0	R-0	R-0	R-0	R-1
7	6	5	4	3	2	1	0
DID7	DID6	DID5	DID4	DID3	DID2	DID1	DID0
R-0	R-0	R-0	R-1	R-0	R-1	R-1	R-1

表 8-14. Device ID Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15:12	Rev[3:0]	R	2h	Indicates the revision number.
11:0	DID[11:0]	R	117h	Indicates the device ID.

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9 Device and Documentation Support

9.1 Documentation Support

9.1.1 Related Documentation

For related documentation see the following:

- Texas Instruments, *TMPx75 Temperature Sensor With I²C and SMBus Interface in Industry Standard LM75 Form Factor and Pinout* data sheet
- Texas Instruments, *TMP275 ±0.5°C Temperature Sensor With I²C and SMBus Interface in Industry Standard LM75 Form Factor and Pinout* data sheet
- Texas Instruments, *Design Considerations for Measuring Ambient Air Temperature* application note
- Texas Instruments, *Replacing Resistance Temperature Detectors with the TMP116 Temp Sensor* application note
- Texas Instruments, *Temperature Sensors: PCB Guidelines for Surface Mount Devices* application note
- Texas Instruments, *Precise Temperature Measurements With the TMP116 and TMP117* application note
- Texas Instruments, *Wearable Temperature Sensing Layout Considerations Optimized for Thermal Response* application note

9.2 接收文档更新通知

要接收文档更新通知，请导航至 ti.com 上的器件产品文件夹。点击*通知* 进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查看任何已修订文档中包含的修订历史记录。

9.3 支持资源

TI E2E™ 中文支持论坛是工程师的重要参考资料，可直接从专家处获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题，获得所需的快速设计帮助。

链接的内容由各个贡献者“按原样”提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的使用条款。

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9.5 静电放电警告



静电放电 (ESD) 会损坏这个集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理和安装程序，可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

9.6 术语表

TI 术语表　　本术语表列出并解释了术语、首字母缩略词和定义。

10 Revision History

注：以前版本的页码可能与当前版本的页码不同

DATE	REVISION	NOTES
January 2024	*	Initial Release

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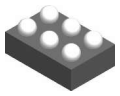
11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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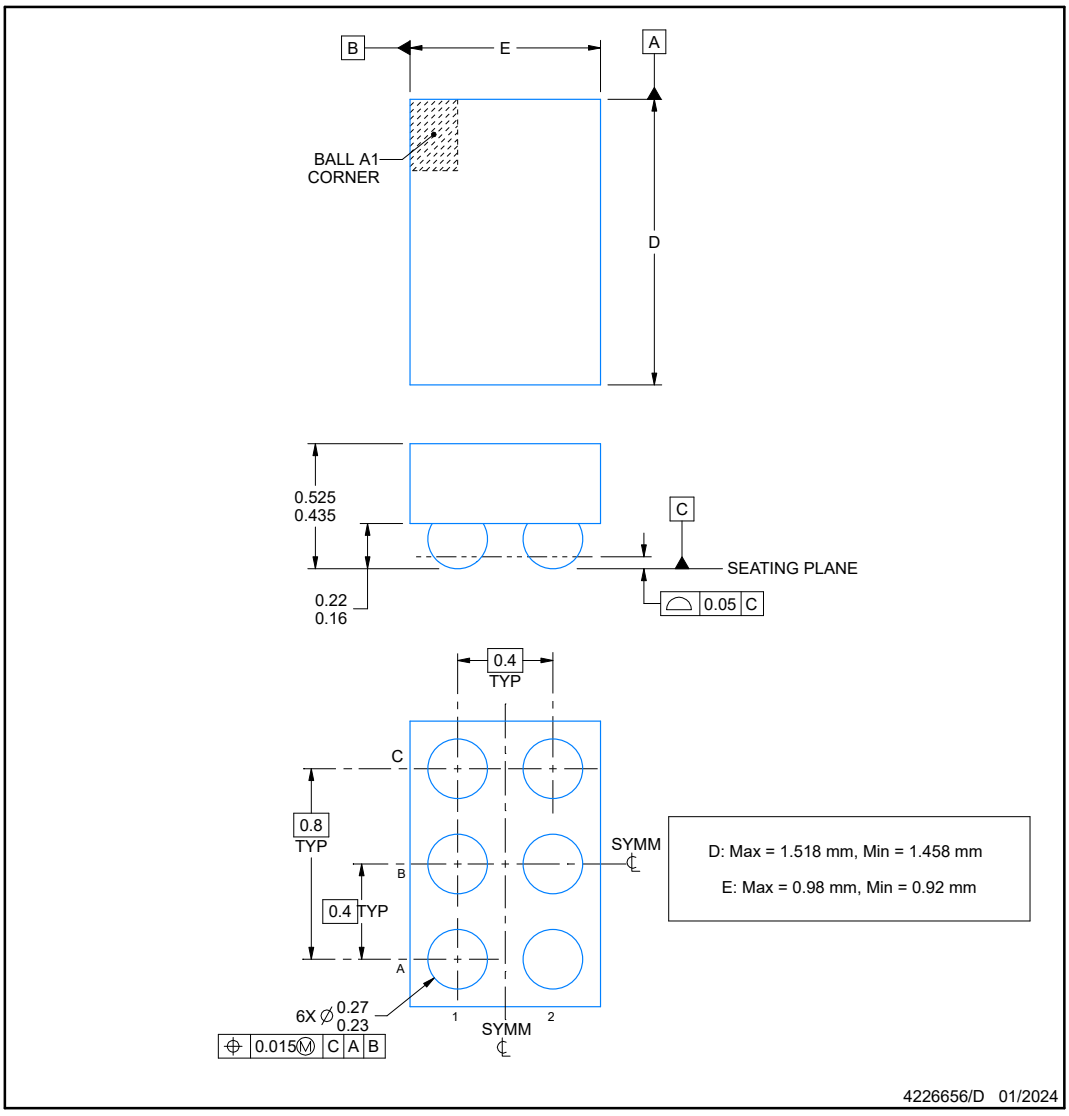
PACKAGE OUTLINE

YBG0006-C01



DSBGA - 0.525 mm max height

DIE SIZE BALL GRID ARRAY



NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

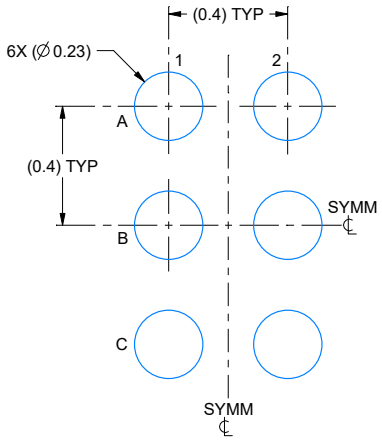
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EXAMPLE BOARD LAYOUT

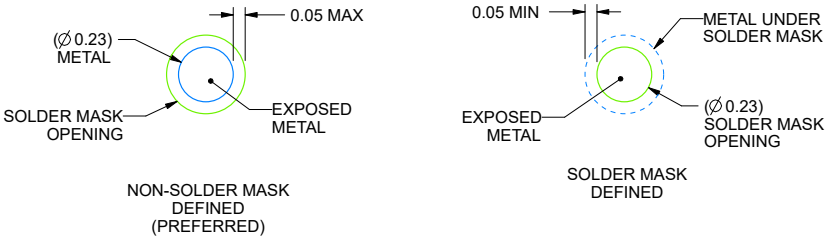
YBG0006-C01

DSBGA - 0.525 mm max height

DIE SIZE BALL GRID ARRAY



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 50X



SOLDER MASK DETAILS
NOT TO SCALE

4226656/D 01/2024

NOTES: (continued)

3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).

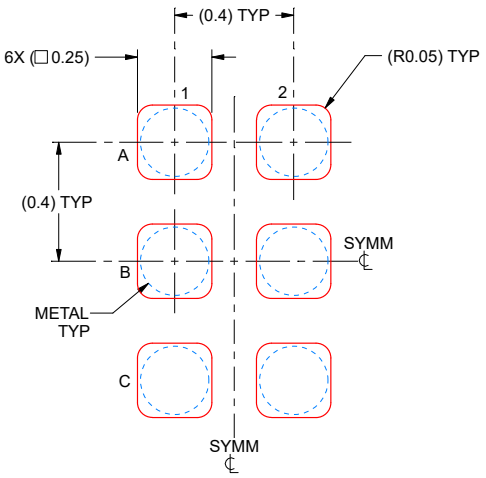
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EXAMPLE STENCIL DESIGN

YBG0006-C01

DSBGA - 0.525 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE: 50X

4226656/D 01/2024

NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

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PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TMP119AIYBGR	Active	Production	DSBGA (YBG) | 6	3000 | LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-55 to 150	OQ
TMP119AIYBGR.A	Active	Production	DSBGA (YBG) | 6	3000 | LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-55 to 150	OQ

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

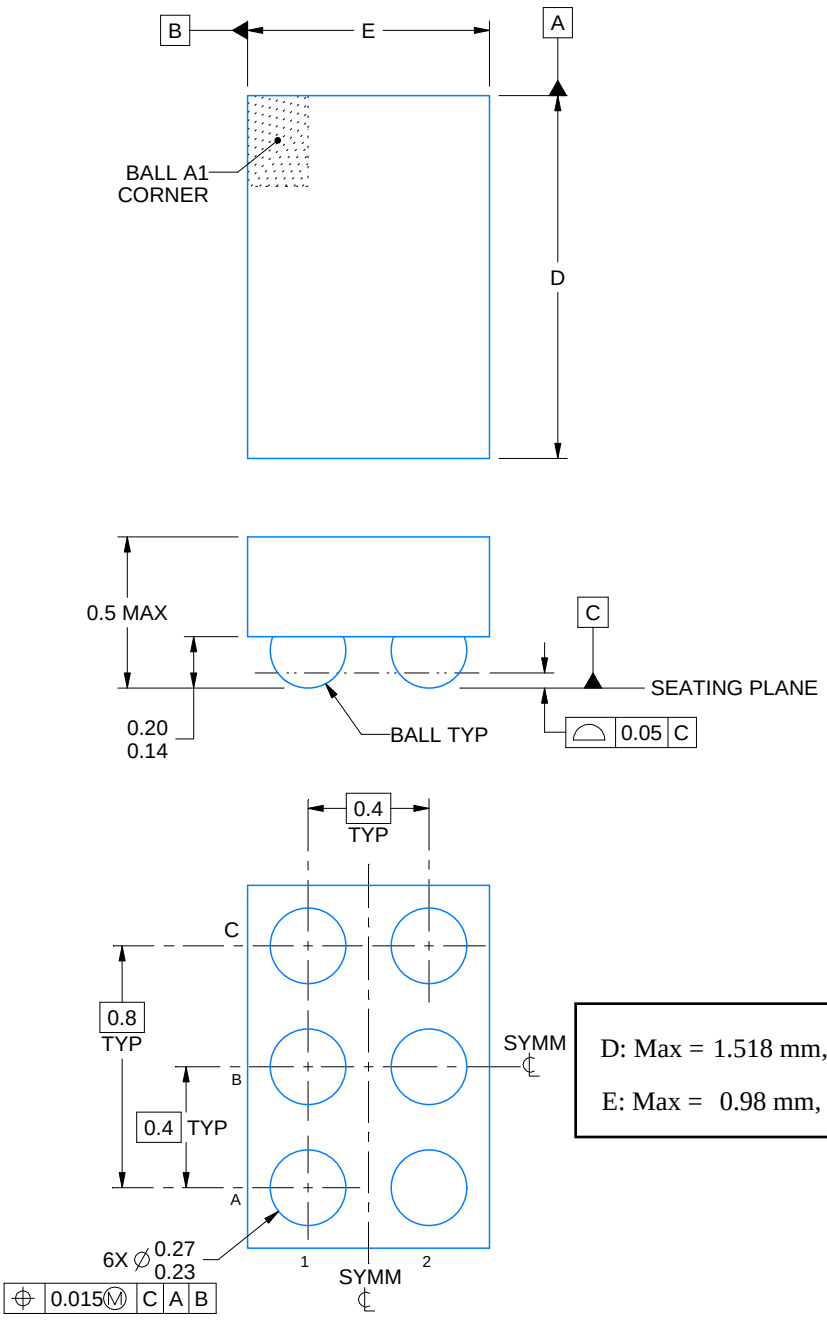
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE OUTLINE

YBG0006

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



4224328/A 05/2018

NOTES:

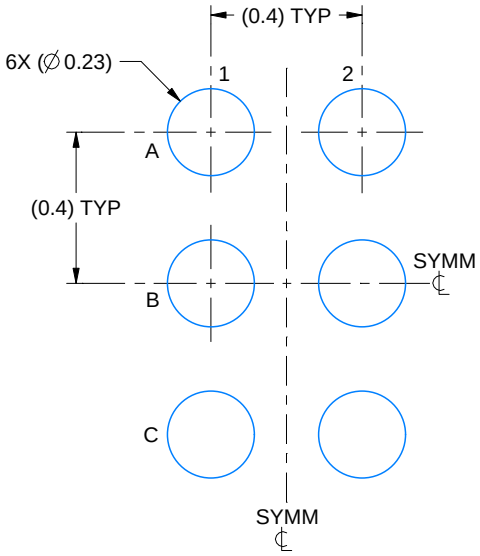
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

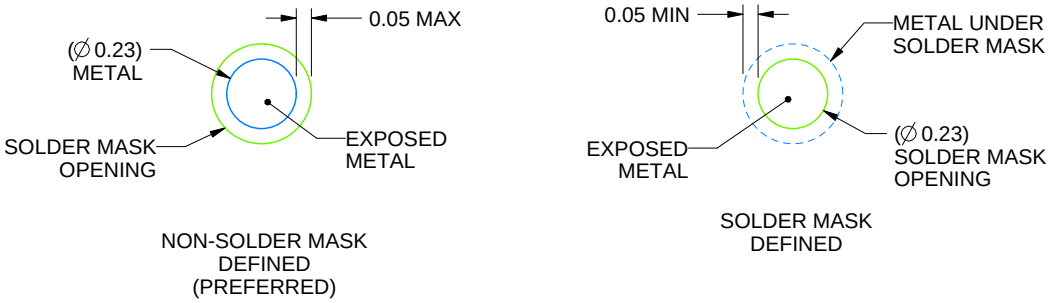
YBG0006

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 50X



SOLDER MASK DETAILS
NOT TO SCALE

4224328/A 05/2018

NOTES: (continued)

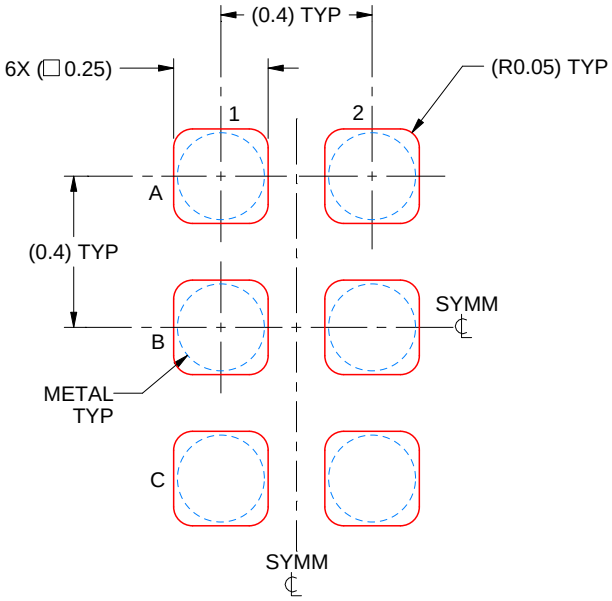
3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints.
   See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).

EXAMPLE STENCIL DESIGN

YBG0006

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE: 50X

4224328/A 05/2018

NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

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最后更新日期：2025 年 10 月